550 Series Positioning Tables



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Single or Multiple Axis

Introduction

LINTECH's 550 series positioning tables offer precision performance and design flexibility for use in a wide variety of Motion Control applications.

- Welding
- Test Stands
- GluingPick & Place
- Part InsertionLaser Positioning
- Liquid Dispensing
- Part Scanning
 Inspection Stations
 - General Automation
- Semiconductor Processing

Quality Construction

LINTECH's 550 series tables are designed to handle large loads at very high speeds. These tables use a low friction, preloaded, recirculating linear ball bearing system, which rides on a single precision ground linear rail. The single linear rail is mounted to a precision machined aluminum base, which offers a rigid support over the entire travel of the table's carriage. The load is mounted to a precision machined aluminum carriage, which has slots machined into it. These slots, along with the base mounting brackets, are used for the mounting of the user load. The drive system uses two pulleys, along with a high strength, steel reinforced polyurethane belt, which provides 8.071 inches (205 mm) of linear movement per revolution of the input shaft. The simple belt tensioning system allows for easy adjustment of belt tension by the user. The belt also acts as a cover, preventing debris from getting into the linear bearings & rail.

The 553 carriage uses 2 high load capacity linear bearings on one precision ground square rail. Both bearings are connected to an internal lubrication network. Any of the 4 lube ports, located on the carriage surface, can be used to supply lubrication to the 2 linear bearings.

The 554 carriage uses 2 high load capacity linear bearings on one precision ground square rail. Both bearings are out-fitted with a self-lubricating material which eliminates the need for regular lubrication. No lube ports are provided on the carriage surface.

The 555 carriage uses 2 high load capacity linear bearings on one precision ground square rail. A unique ball retainer design for the recirculating linear bearings provides a smoother operating system with less audible noise. Both bearings are connected to an internal lubrication network. Any of the 4 lube ports, located on the carriage surface, can be used to supply lubrication to the 2 linear bearings.

Available Options

Carriage Adapter Plates & Vertical Angle Brackets

Optional carriage adapter plates and vertical angle brackets can be mounted directly to the top of various LINTECH positioning tables, thus providing for easy multiple axis configurations.

End of Travel and Home Switches

The 550 series tables can be provided with end of travel (EOT) and home switches mounted and wired for each axis. Most position controllers can utilize the EOT switches to stop carriage motion when the extreme table travel has been reached in either direction. The home switch provides a known mechanical location on the table.

Motor Adapter Brackets

NEMA 34, NEMA 42, or any metric mount motor can be mounted to a 550 series positioning table with the use of adapter brackets.

Rotary Encoders

Incremental rotary encoders can be mounted to the table in order to provide positional data back to either a motion controller, or a digital display.

Planetary Gearheads

LINTECH provides planetary gearheads which can be used with a 550 series. These gearheads are provided in either an in-line or right angle version, with standard gear ratios of 1:1, 3:1, 5:1 or 10:1. Gearheads may be required for applications which have a large mismatch of load to motor inertias. They also help reduce the torque required from the motor for a particular application.

Other

The 550 series tables can accommodate **chrome plated linear bearings & rails** for corrosive environment applications and **power-off electric brakes** for load locking applications.

Standard Features - 550 Series

- 10.236 inches (260 mm) long carriage with two M5 slots for load mounting
- Compact 3.15 inches (80 mm) wide by 3.937 inches (100 mm) tall
- Travel lengths from 12 inches (300 mm) to 30 feet (9,1 meters)
- Rigid belt driven design with fully enclosed aluminum housing
- 0° F to +176° F (-18° C to +80° C) operating temperature
- Two screw belt tensioning with self locking threads
- Dynamic Load Capacity to 12,650 lbs (5740 kg)
- Recirculating linear ball bearing system
- Precision ground square rail design
- 1 rail with 2 bearing carriages



- Less expensive than the 555 carriage
- Large moment load capability



- Two bearing carriage
- 12,650 lbs (5740 kg) dynamic load capacity
- 560 ft-lbs (760 N-m) dynamic roll moment
- Less audible noise than the 553 or 554 series
- Smoother than the 553 or 554 carriage
- Unique linear bearing design



- □ 560 ft-lbs (760 N-m) dynamic roll moment
- Self lubricating linear bearings
- Large moment load capability

Options - 550 Series Angle brackets for multiple axis configurations End of travel (EOT) and home switches wired CAD drawings available via the internet Chrome plated linear bearings and rails Motor mounts for non-NEMA motors NEMA 34 & 42 motor mounts Rotary incremental encoders Power-off electric brakes Base mounting brackets

- Carriage adapter plates
- Planetary gearheads
- Motor couplings

Ordering Guide

			553	10 01	2 - D1 -	M04 - C	-293	L04	- E00	- B
Table Series										
553 - 553 carriag	ie									
554 - 554 carriag										
555 - 555 carriag	je									
Carriage Length										
10 - 10 inches										
Travel Length (see	e page K-6)									
012 - 12 to 360 i	inches									
Drive Shaft (see pa	age K-7)									
D1 - Right Hand	single shaft	D3 - Right	Hand thru sh	naft						
	ingle shaft									
Motor Mount (see	page K-20)									
	shaft extension	M04 - NEM	1A 34 mount	(E) M10 -	NEMA 42 moun	t (E)				
M99 - other		M05 - NEM	IA 34 mount		NEMA 42 moun					
	s (see pages K-24 & K			(M) M11 -						
	(see pages K-24 & K C293 to C303	(-25)		(M) M11 -		t (M)				
Coupling Options		(-25) 3 - H197	C573 to C	(M) M11 -	NEMA 42 moun	t (M)				
Coupling Options C000 - none C999 - none	C293 to C303 C359 to C369	(-25) 3 - H197 9 - H225	C573 to C C639 to C	(M) M11 - 1 583 - G177 649 - G220	NEMA 42 moun C684 to C6 9	t (M)				
Coupling Options C000 - none C999 - none	C293 to C303 C359 to C369 vitches (see pages	(-25) 3 - H197 9 - H225	C573 to C C639 to C	(M) M11 - 1 583 - G177 649 - G220	NEMA 42 moun C684 to C6 9	t (M)				
Coupling Options C000 - none C999 - none Limit & Home Sw	C293 to C303 C359 to C369 vitches (see pages	K-25) - H197 - H225 K-21 to K-23)	C573 to C C639 to C	(M) M11 -	NEMA 42 moun	t (M) 91 - G260				
Coupling Options C000 - none C999 - none Limit & Home Sw L00 - no switches	C293 to C303 C359 to C369 vitches (see pages s	 K-25) H197 H225 K-21 to K-23) switches 	C573 to C C639 to C Reed	(M) M11 - 1 583 - G177 649 - G220 Hall	NEMA 42 mount C684 to C69 Prox (NPN)	t (M) 91 - G260 Prox (PNP)				
Coupling Options C000 - none C999 - none Limit & Home Sw L00 - no switches	C293 to C303 C359 to C369 vitches (see pages s EOT & home EOT switc	 K-25) H197 H225 K-21 to K-23) switches 	C573 to C C639 to C Reed L04	(M) M11 - 583 - G177 5649 - G220 Hall L07	NEMA 42 mount C684 to C69 Prox (NPN) L10	t (M) 91 - G260 Prox (PNP) L13				
Coupling Options C000 - none C999 - none Limit & Home Sw L00 - no switches L99 - other	C293 to C303 C359 to C369 vitches (see pages s EOT & home EOT switc home sv	 K-25) H197 H225 K-21 to K-23) switches ches only vitch only 	C573 to C C639 to C Reed L04 L05 L06	(M) M11 - 583 - G177 649 - G220 Hall L07 L08 L09	NEMA 42 mount C684 to C69 Prox (NPN) L10 L11 L12	et (M) 1 - G260 Prox (PNP) L13 L14				
Coupling Options C000 - none C999 - none Limit & Home Sw L00 - no switches L99 - other	C293 to C303 C359 to C369 vitches (see pages s EOT & home EOT switc home sv (see page K-27)	 K-25) H197 H225 K-21 to K-23) switches ches only vitch only 	C573 to C C639 to C Reed L04 L05 L06	(M) M11 - 583 - G177 649 - G220 Hall L07 L08 L09	NEMA 42 moun C684 to C69 Prox (NPN) L10 L11 L12	et (M) 1 - G260 Prox (PNP) L13 L14				
Coupling Options C000 - none C999 - none Limit & Home Sw L00 - no switches L99 - other Encoder Options	C293 to C303 C359 to C369 vitches (see pages s EOT & home EOT switc home sv (see page K-27) E0:	 K-25) H197 H225 K-21 to K-23) switches switches only vitch only rotary (1 	C573 to C C639 to C Reed L04 L05 L06	(M) M11 - 583 - G177 649 - G220 Hall L07 L08 L09) E99 -	NEMA 42 moun C684 to C69 Prox (NPN) L10 L11 L12	et (M) 1 - G260 Prox (PNP) L13 L14				
Coupling Options C000 - none C999 - none Limit & Home Sw L00 - no switches L99 - other Encoder Options E00 - none E01 - rotary (500	C293 to C303 C359 to C369 vitches (see pages s EOT & home EOT switc home sv (see page K-27) E0:	 K-25) H197 H225 K-21 to K-23) switches switches only vitch only vitch only rotary (1 rotary (1 	C573 to C C639 to C Reed L04 L05 L06 000 lines/rev 270 lines/rev	(M) M11 - 583 - G177 649 - G220 Hall L07 L08 L09) E99 -	NEMA 42 mount C684 to C69 Prox (NPN) L10 L11 L12 other	et (M) 1 - G260 Prox (PNP) L13 L14				
Coupling Options C000 - none C999 - none Limit & Home Sw L00 - no switches L99 - other Encoder Options E00 - none E01 - rotary (500 note: When se	C293 to C303 C359 to C369 vitches (see pages s EOT & home EOT switc home sv (see page K-27)	 K-25)	C573 to C C639 to C Reed L04 L05 L06 000 lines/rev 270 lines/rev the Drive Shar	(M) M11 - 583 - G177 649 - G220 Hall L07 L08 L09) E99 -) ft D3 or D4 above	NEMA 42 mount C684 to C69 Prox (NPN) L10 L11 L12 other ve is required.	et (M) P1 - G260 Prox (PNP) L13 L14 L15				
Coupling Options C000 - none C999 - none Limit & Home Sw L00 - no switches L99 - other Encoder Options E00 - none E01 - rotary (500 note: When se	C293 to C303 C359 to C369 vitches (see pages s EOT & home EOT switc home sv (see page K-27)	 K-25)	C573 to C C639 to C Reed L04 L05 L06	(M) M11 - 583 - G177 649 - G220 Hall L07 L08 L09) E99 -) ft D3 or D4 above	NEMA 42 mount C684 to C69 Prox (NPN) L10 L11 L12 other ve is required.	et (M) P1 - G260 Prox (PNP) L13 L14 L15				

(E) - English Interface (M) - Metric Interface

- Belt Drive -

Specifications

Load Capacities		55	53 & 554	Carr	riages	S		555 C	arri	age	
Dynamic Horizontal 2	2 million inches (50 km) of travel	12,650	lbs	(5	5740	kg)	12,650	lbs	(5740	kg)
Dynamic Horizontal 100) million inches (2540 km) of travel	3,400	lbs	(1	1540	kg)	3,400	lbs	(1540	kg)
Static Horizontal		19,000	lbs	(8	8620	kg)	19,000	lbs	(8620	kg)
Dynamic Roll Moment 2	2 million inches (50 km) of travel	560	ft-lbs	(760	N-m)	560	ft-lbs	(760	N-m)
Dynamic Roll Moment 100) million inches (2540 km) of travel	150	ft-lbs	(200	N-m)	150	ft-lbs	(200	N-m)
Static Roll Moment		790	ft-lbs	(1	1070	N-m)	790	ft-lbs	(1070	N-m)
Dyn. Pitch & Yaw Moment 2	2 million inches (50 km) of travel	1,710	ft-lbs	(2	2320	N-m)	1,710	ft-lbs	(2320	N-m)
Dyn. Pitch & Yaw Moment 100) million inches (2540 km) of travel	460	ft-lbs	(625	N-m)	460	ft-lbs	(625	N-m)
Static Pitch & Yaw Moment		1,775	ft-lbs	(2	2406	N-m)	845	ft-lbs	(1145	N-m)
Each Bearing Dyn. Capacity 2	2 million inches (50 km) of travel	6,325	lbs	(2	2870	kg)	6,325	lbs	(2870	kg)
Each Bearing Dyn. Capacity 100) million inches (2540 km) of travel	1,700	lbs	(770	kg)	1,700	lbs	(770	kg)
Each Bearing Static Load Capa	city	9,500	lbs	(4	4310	kg)	9,500	lbs	(4310	kg)
Maximum Belt Tensile Force		675	lbs	(306	kg)	675	lbs	(306	kg)
Maximum Carriage Thrust Force	е	475	lbs	(215	kg)	475	lbs	(215	kg)
Maximum Speed		118	in/sec	(3	m	n/sec)	197	in/sec	(5 n	n/sec)
Maximum Acceleration		1,930	in/sec ²	(49	,0 m/	/sec²)	1,930	in/sec ²	(4	19,0 m	/sec²)
d ₂ Center to center distance (spacing)	of each bearing on a single rail	3.	876 in	(98	,4	mm)	3.	876 in	(9	98,4	mm)
d _r Center distance of the bearing to top	p of carriage plate surface	1.	508 in	(38	,3	mm)	1.	626 in	(4	1,3	mm)

Other	553, 554 & 555 Carriages						
Table Material	Base Extrusion, Carriage, & End Plates - 6061 anodized aluminum						
Linear Rail Material	Case Hardened Steel						
Belt Properties	Black, 50 mm wide, Polyurethane, Steel reinforced belt						
Drive Pulley Weight	1.500 lbs (0,68 kg)						
Drive Pulley Diameter	2.569 in (65,25 mm)						
Drive Lead	8.071 in (205,00 mm)						
Belt Stretch - x Load (lbs or N)	0.00006 in/ft per lbs (0,00114 mm/m per N)						
Unidirectional Repeatability	+/- 0.001 in (+/- 0,0254 mm)						
Bidirectional Repeatability	+/- 0.004 in (+/- 0,1016 mm)						
Position Accuracy (Belt) (1)	< 0.010 in/ft (< 0,254 mm/300mm)						
Orthogonality (multi-axis systems)	< 60 arc-seconds						
Friction Coefficient	< 0.01						
Breakaway Torque ⁽²⁾	< 16 lb-in (1,808 N-m)						
Motor Mount	NEMA 34 & 42 Mounts, Metric Mounts, and Gearheads						
Coupling	Two (2) different styles available						

Footnotes:

(1) Position accuracy varies based on belt stretch. The given rating is based upon a carriage speed of 5 inches/sec (127 mm/sec) and a no load condition.

(2) This is a nominal value. Breakaway torque will increase, or decrease, based on belt tension.

K-5

Dimensions & Specifications

Model Number	Travel ⁽¹⁾ Length inches	inc	mensions hes ım)	Belt Weight Ibs	Table Weight (553 & 554 Carriages) Ibs	Table Weight (555 Carriage) Ibs	
	(mm)	А	В	(kg)	(kg)	(kg)	
55x10012	12	24.00	32.275	0.29	24.1	23.0	
	(300)	(609,6)	(819,8)	(0,13)	(10,9)	(10,4)	
55x10018	18	30.00	38.275	0.40	27.3	26.0	
	(455)	(762,0)	(972,2)	(0,18)	(12,4)	(11,8)	
55x10024	24	36.00	44.275	0.51	30.6	29.2	
	(605)	(914,4)	(1124,6)	(0,23)	(13,9)	(13,2)	
55x10030	30	42.00	50.275	0.62	33.9	32.3	
	(760)	(1066,8)	(1277,0)	(0,28)	(15,4)	(14,7)	
55x10036	36	48.00	56.275	0.72	37.2	35.5	
	(910)	(1219,2)	(1429,4)	(0,33)	(16,9)	(16,1)	
55x10048	48	60.00	68.275	0.94	43.8	41.8	
	(1215)	(1524,0)	(1734,2)	(0,43)	(19,9)	(19,0)	
55x10060	60	72.00	80.275	1.15	50.3	48.0	
	(1520)	(1828,8)	(2039,0)	(0,52)	(22,8)	(21,8)	
55x10072	72	84.00	92.275	1.37	56.9	54.3	
	(1825)	(2133,6)	(2343,8)	(0,62)	(25,8)	(24,6)	
55x10084	84	96.00	104.275	1.58	63.5	60.6	
	(2130)	(2438,4)	(2648,6)	(0,72)	(28,8)	(27,5)	
55x10096	96	108.00	116.275	1.80	70.1	66.9	
	(2435)	(2743,2)	(2953,4)	(0,82)	(31,8)	(30,3)	
55x10108	108	120.00	128.275	2.01	76.7	73.2	
	(2740)	(3048,0)	(3258,2)	(0,91)	(34,8)	(33,2)	
55x10120	120	132.00	140.275	2.23	83.2	79.4	
	(3045)	(3352,8)	(3563,0)	(1,01)	(37,8)	(36,0)	
55x10132	132	144.00	152.275	2.44	89.8	85.7	
	(3350)	(3657,6)	(3867,8)	(1,11)	(40,8)	(38,9)	
55x10144	144	156.00	164.275	2.66	96.4	92.0	
	(3655)	(3962,4)	(4172,6)	(1,21)	(43,7)	(41,7)	
55x10180	180	192.00	200.275	3.30	116.1	110.8	
	(4572)	(4876,8)	(5087,0)	(1,50)	(52,7)	(50,3)	
55x10240	240	252.00	260.275	4.38	149.0	142.2	
	(6096)	(6400,8)	(6611,0)	(1,99)	(67,6)	(64,5)	
55x10300	300	312.00	320.275	5.45	181.9	173.6	
	(7620)	(7924,8)	(8135,0)	(2,47)	(82,5)	(78,7)	
55x10360	360	372.00	380.275	6.52	214.8	204.9	
	(9144)	(9448,8)	(9659,0)	(2,96)	(97,4)	(92,9)	

x = 3; 553 Carriage; Carriage weight = 7.98 lbs. (3,62 kg) x = 4; 554 Carriage; Carriage weight = 7.98 lbs. (3,62 kg) x = 5; 555 Carriage; Carriage weight = 7.14 lbs. (3,24 kg)

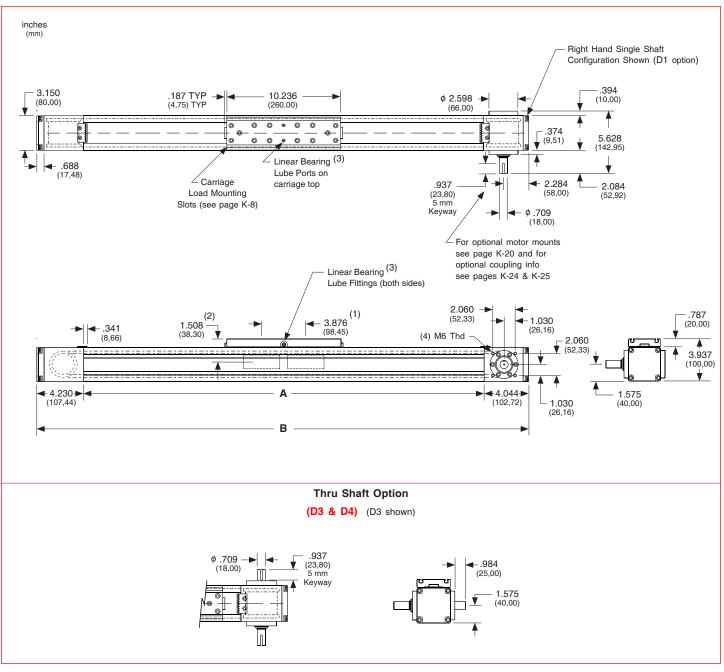
Footnotes:

(1) Longest possible travel is 30 feet (9,1 meters). Any travel length less than 30 feet (9,1 meters) can be provided.

Specifications subject to change without notice

- Belt Drive -

Dimensions



Footnotes:

(1) This value is center to center distance (spacing) of each bearing on a single rail (d_2) .

- (2) This value is the center distance of the bearing to top of carriage plate surface (d_r) for the 553 & 554 carriages. For the 555 carriage $d_r = 1.626$ inches (41,3 mm).
- (3) Two lube ports on carriage top and lube fittings on each side of the 553 & 555 carriages are all interconnected. Only one port is required to lubricate both linear bearings. The 554 carriage will not have any lube ports.

Carriage Fastener Rail & Base Mounting Brackets

LINTECH provides the user with 2 vital optional accessories. The carriage fastener rails slide into the two slots on the 550 series carriage. These fastener rails give the user the ability to mount their load to the 550 series carriage. From 1 to 3 fastener rails can be used in each carriage slot. The base mounting brackets give the user the ability to mount the 550 series table to a mounting surface. These mounting brackets attach anywhere along the bottom T-slot's on both sides of the 550 series table.

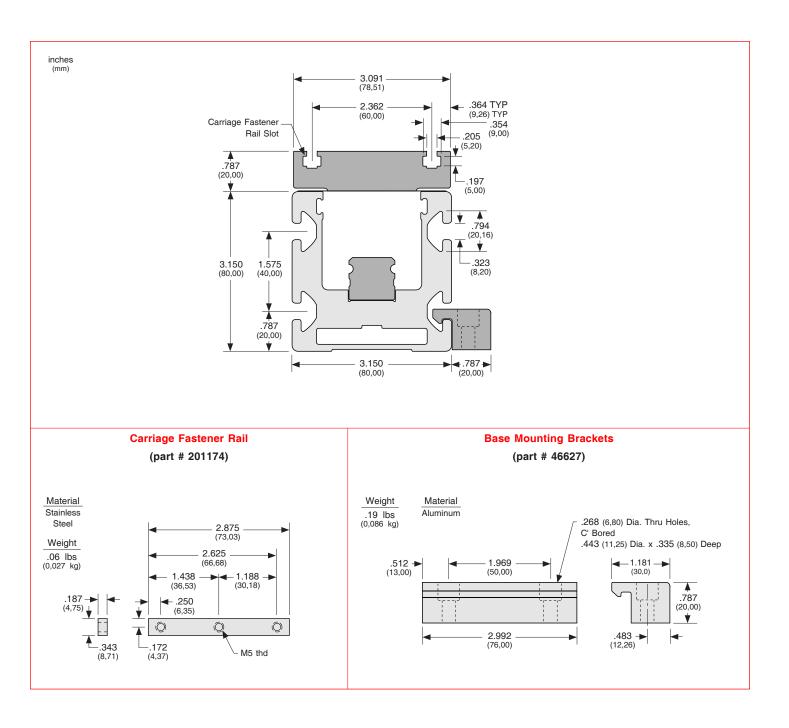
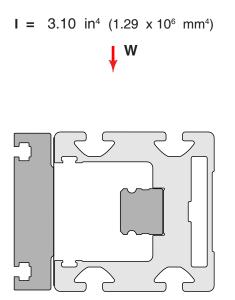
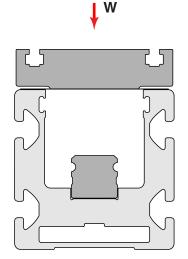


Table Deflection - Moment of Inertia Values

The "moment of inertia" of an object is a gauge of the strength of that object to resist deflecting when used in an application or orientation where deflection might occur. The higher an I value relates to a lower amount of deflection.





 $I = 4.44 \text{ in}^4 (1.85 \times 10^6 \text{ mm}^4)$

- Belt Drive -

travel life

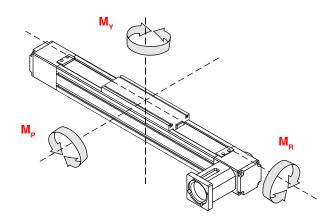
555 Carriage

Linear Bearing Load Capacities

The following equation, and graphs, can be used to help determine the linear bearing life, and load capacity, of a 550 series positioning table.

$$L = \left[\frac{R}{F \times S}\right]^3 \times B$$

- L = calculated travel life (millions of inches or Km)
- **R** = rated dynamic load capacity of carriage (or each bearing) at 2 million inches of travel or 50 Km
- F = user applied load
- S = safety factor (1 to 8)
- **B** = either 2 (for millions of inches) or 50 (for Km)



Dynamic Moment Load (M_B) Capacity

Load applied away from Carriage Center

			0		
travel lif	e	553 & 554	Carriage	555 Ca	arriage
millions of inches	(Km)	ft-lbs	(N-m)	ft-lbs	(N-m)
2	(50)	560	(760)	560	(760)
50	(1270)	190	(258)	190	(258)
100	(2540)	150	(200)	150	(200)
Ratin	igs are base	ed on d ₃ = 12 i	inches (305 m	nm) & $d_4 = 0$	

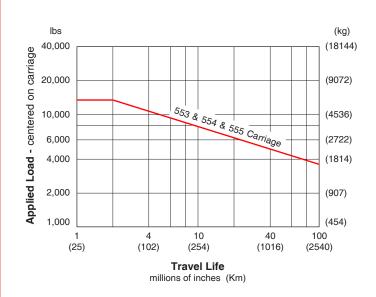
ft-lbs (N-m) 1,000 (1356) Applied Load - from carriage center 600 (813) 553 & 554 & 555 Carriage 400 (542) 200 (271)100 (136) 60 (81) 40 (54) 20 (27) 4 10 40 100 1 (25) (102) (254) (1016) (2540) Travel Life millions of inches (Km)

	-				
millions of inches	(Km)	lbs	(kg)	lbs	(kg)
2	(50)	12,650	(5740)	12,650	(5740)
50	(1270)	4,325	(1960)	4,325	(1960)
100	(2540)	3,400	(1540)	3,400	(1540)

Dynamic Horizontal Load Capacity

Load Centered on Carriage

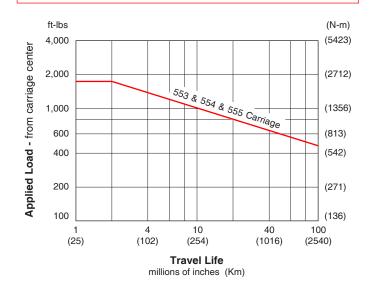
553 & 554 Carriage



Dynamic Moment Load ($M_P \& M_Y$) Capacity

Load applied away from Carriage Center

travel lif	e	553 & 554	Carriage	555 C	arriage
millions of inches	(Km)	ft-lbs	(N-m)	ft-lbs	(N-m)
2	(50)	1,710	(2320)	1,710	(2320)
50	(1270)	585	(790)	585	(790)
100	(2540)	460	(625)	460	(625)
Ratin	igs are base	ed on $d_3 = 0$ &	$d_4 = 12$ inche	es (305 mm)	





Maximum Motor Input Torque, Maximum Belt Force, & Maximum Acceleration Rate

Maximum Motor Input Torque

The maximum safe speed/torque of a motor/drive system that can be used with the 550 series, is limited by the belt strength at a given speed. The maximum linear forces the belt can adequately handle are determined by the number of teeth on the pulley and the belt width. The chart below illustrates the relationship between motor input torque/belt force and carriage speed. Care should be taken when sizing and selecting a motor/drive system for use with a 550 series table. Exceeding the maximum input torque values at the listed speeds can cause belt "skipping" over pulley teeth. This will result in mis-positioning of the carriage.

Maximum Acceleration

The maximum acceleration rate using a 550 series table can be determined by the simple equation $\mathbf{F} = \mathbf{M} \mathbf{x} \mathbf{A}$. Knowing the mass of the load, and the maximum safe operating force for the belt, the maximum possible acceleration rate can be determined. Note: The mechanical limitation for acceleration of the 550 series table is 5 g's.

Maximum Acceleration Example

F	=	M × A
F	=	maximum belt force at desired speed
Μ	=	user applied load
Α	=	maximum acceleration rate (g's)
Sin Ø	=	angle of table from horizontal (degrees)

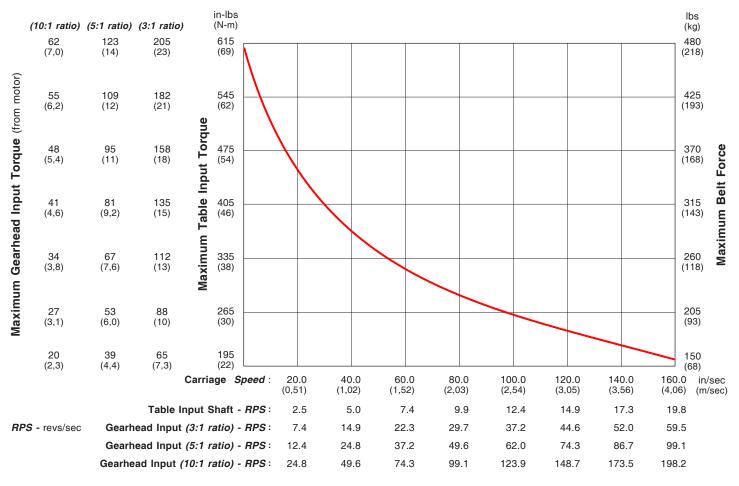
Horizontal Application Vertical Application A = _

$$\frac{F - M \sin \varphi}{M}$$

- Example: A 200 lb load is mounted to a 550 series carriage in a horizontal application. Determine the maximum accel rate in g's & in/sec2 that can be used to achieve a maximum speed of 75 IPS.
 - Step 1: From graph below, determine the maximum belt force at 75 IPS : (F = 235 lbs).
 - Step 2: Add up your total mass = load weight + carriage weight : (M = 5.4 + 200 = 205.4 lbs).
 - Step 3: Solve for A : (A = 235/205.4 = 1.1 g's).

Note: 1 g = 386 in/sec²

Step 5: 1.1 g's x 386 = 442 in/sec².

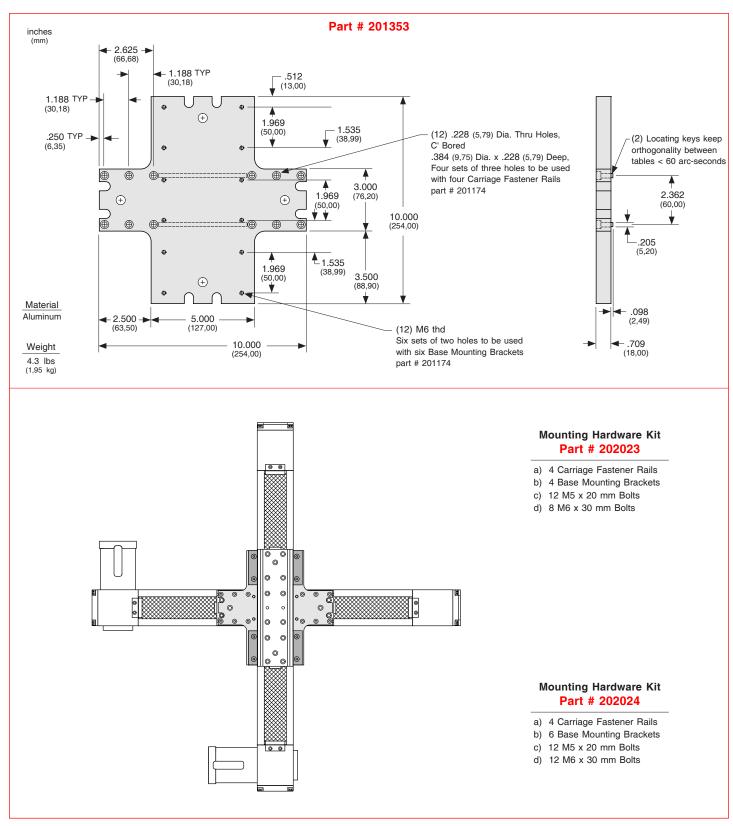


1) Table friction & breakaway forces have already been deducted from the above maximum belt force values.

2) Curve based upon maximum belt values. Select a motor coupling that can handle the required torque.

Carriage Adapter Plate (550 Base to 550 Carriage)

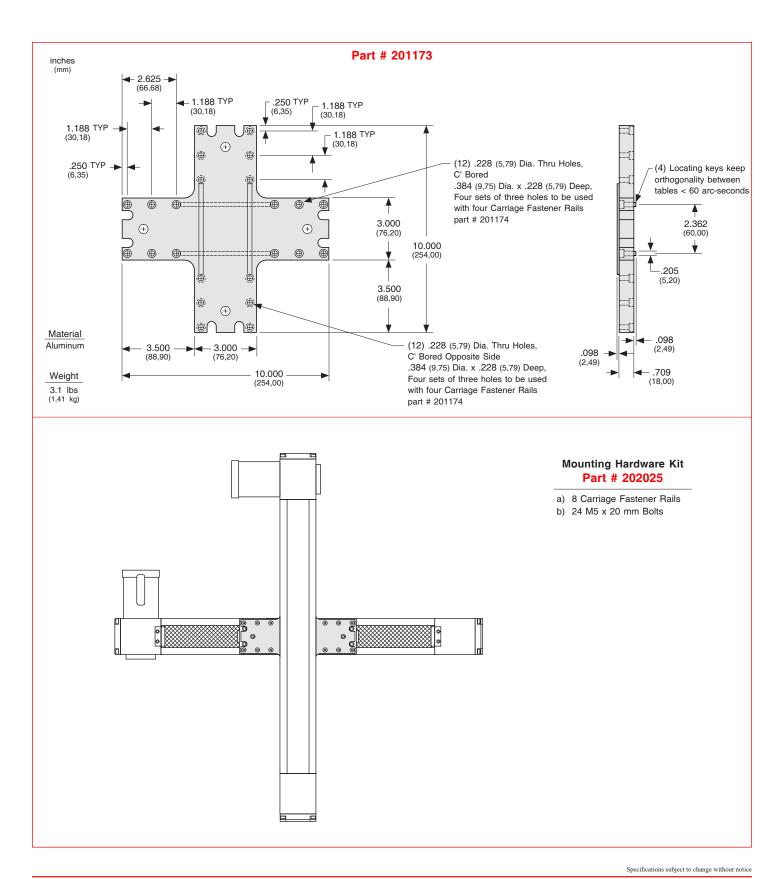
Optional carriage adapter plates assist in the creation of simple X-Y, X-Z, and X-Y-Z multiple axis systems. Using one of the adapter plates below, allows a 550 series table to be mounted on top of a second 550 series table in order to make an X-Y axes system (see below). Also, using two of the adapter plates below, allows a 550 series table to be mounted on top of two 550 series tables in order to make an X-Y axes gantry system (see page K-14).





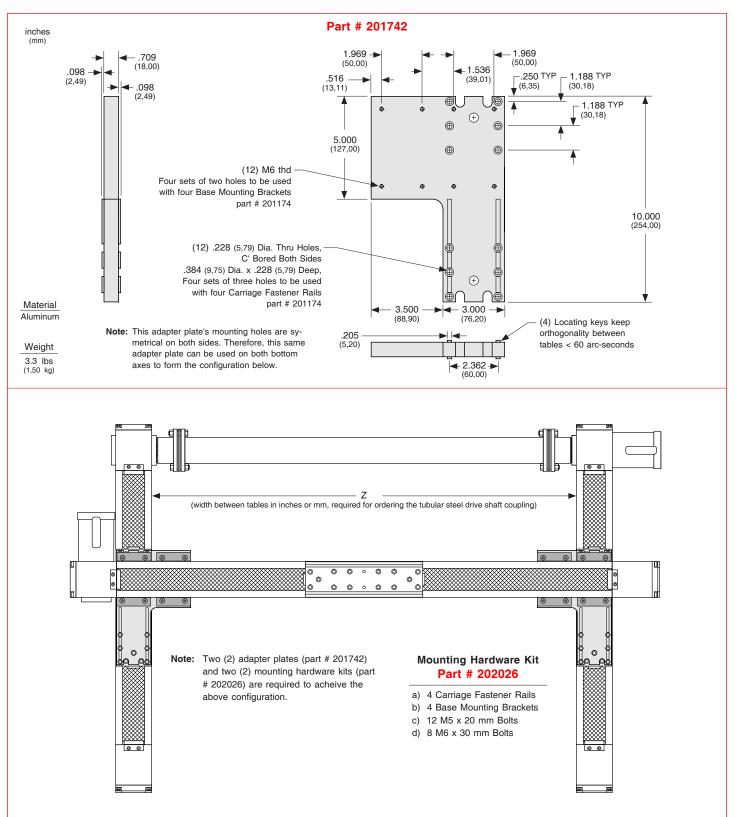
Carriage Adapter Plate (550 Carriage to 550 Carriage)

Optional carriage adapter plates assist in the creation of simple X-Y, X-Z, and X-Y-Z multiple axis systems. The adapter plate below allows two 550 series tables to be mounted carriage to carriage in order to make an X-Y axes system.



Carriage Adapter Plate (550 Base to 550 Carriage)

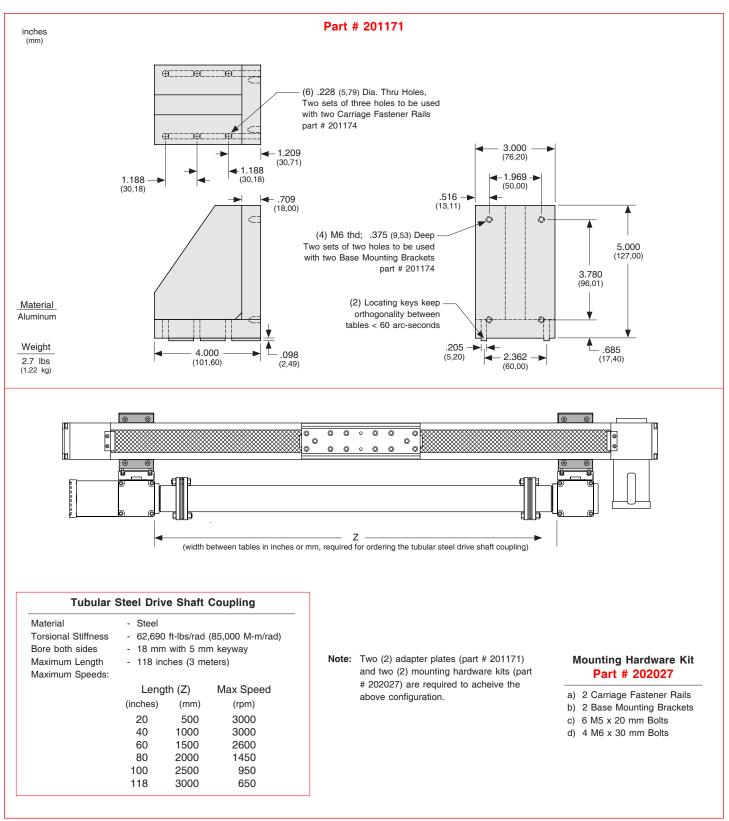
Optional carriage adapter plates assist in the creation of simple X-Y, X-Z, and X-Y-Z multiple axis systems. Using one of the adapter plates below, allows a 550 series table to be mounted on top of a second 550 series table in order to make an X-Y axes system (see page K-12). Also, using two of the adapter plates below, allows a 550 series table to be mounted on top of two 550 series tables in order to make an X-Y axes gantry system (see below).





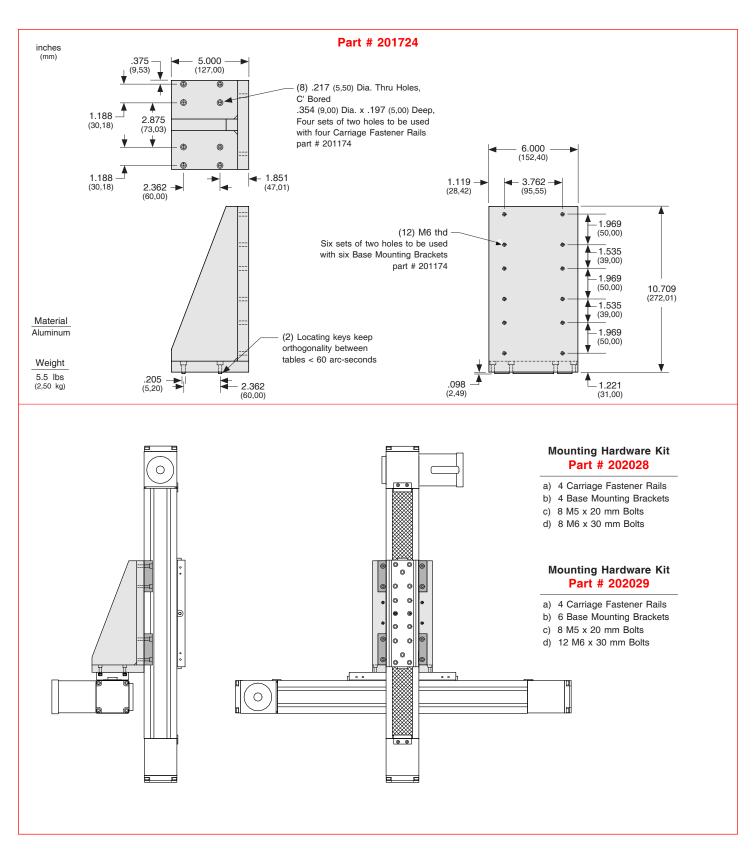
Horizontal Adapter Bracket (550 Series Base to 550 Carriage)

Optional horizontal adapter brackets assist in the creation of simple X-Y, X-Z, and X-Y-Z multiple axis systems. Using one of the adapter plates below, allows a 550 series table to be mounted on top of a second 550 series table in order to make an X-Y axes system. Also, using two of the adapter plates below, allows a 550 series table to be mounted on top of two 550 series tables in order to make an X-Y axes gantry system (see below).



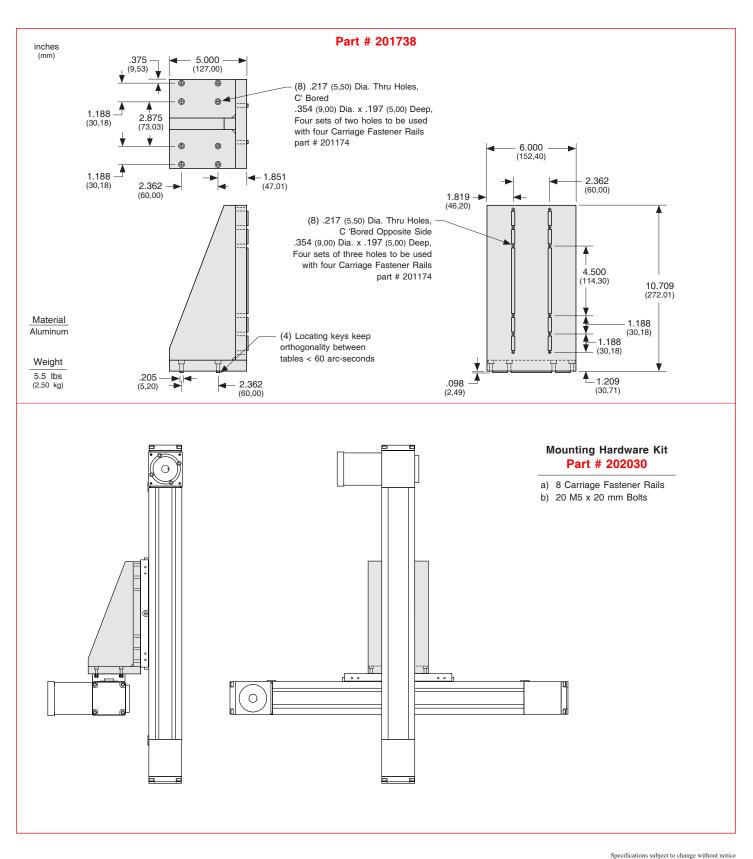
Vertical Adapter Bracket (550 Base to 550 Carriage)

Optional vertical adapter brackets assist in the creation of simple X-Y, X-Z, and X-Y-Z multiple axis systems. The vertical adapter bracket below allows a 550 series table to be mounted on top of a second 550 series table in order to make an X-Z axes system.



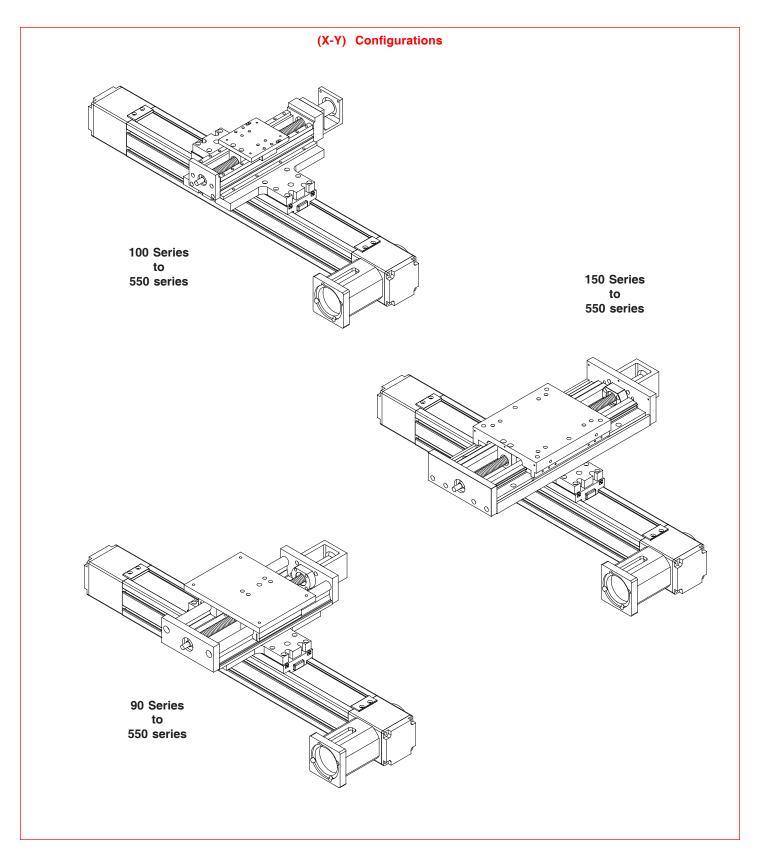
Vertical Adapter Bracket (550 Carriage to 550 Carriage)

Optional vertical adapter brackets assist in the creation of simple X-Y, X-Z, and X-Y-Z multiple axis systems. The vertical adapter bracket below allows two 550 series tables to be mounted carriage to carriage in order to make an X-Z axes system.



Multi-Axis Configurations

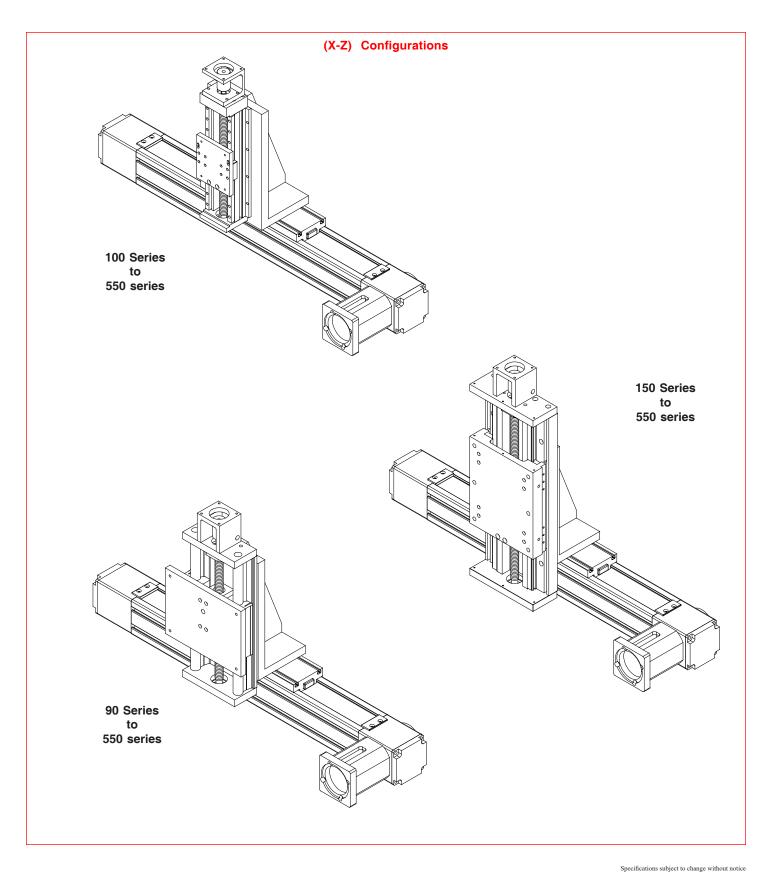
LINTECH can provide various adapter plates, horizontal adapter brackets, and vertical adapter brackets to facilitate the construction of X-Y, X-Z, and X-Y-Z multiple axis configurations using its many different standard positioning systems.





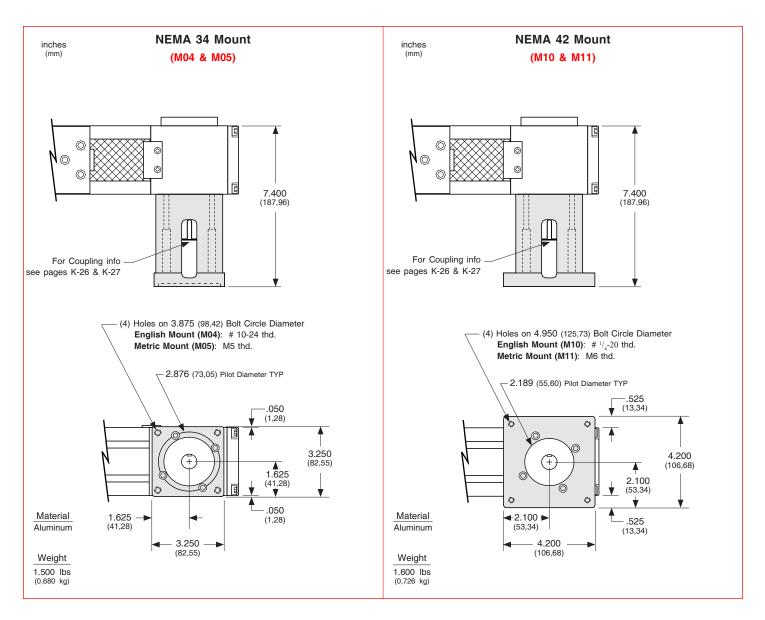
Multi-Axis Configurations

LINTECH can provide various adapter plates, horizontal adapter brackets, and vertical adapter brackets to facilitate the construction of X-Y, X-Z, and X-Y-Z multiple axis configurations using its many different standard positioning systems.



NEMA 34 & NEMA 42 Motor Mounts

NEMA 34 & 42 motor mounts can be ordered with either English, or Metric threads. *LINTECH* can provide adapter brackets for any step motor, or servo motor, that has other mounting requirements.



Chrome Plated Linear Bearings & Rails

For applications in high moisture, high humidity, clean room, or highly corrossive environments, chrome plating of the linear bearings, and linear rails, will offer superior resistance to corrosion than stainless steel components, resulting in longer table life. The process uniformly deposits dense, hard, high chromium alloy on the rails, and has a Rockwell C hardness value of 67-72. This process also conforms to MIL Spec: (MIL-C-23422). The chrome plating bonds to the parent material and will not crack or peel off under the high point loading of balls on the rail. This chrome plating process differs from a normal hard chrome plate which just lays on the surface of the part plated.



End of Travel (EOT) Switches & Home Switch

LINTECH provides several options for EOT & home switches. When ordered with a LINTECH 550 series table, each switch is mounted to the side of the table, while the actuating cams are mounted to the carriage assembly. The *T*-*slot* which runs along both sides of the 550 series, allows the switches to be located anywhere along the table. The switches are pre-wired by LINTECH for easy interfacing to the users Motion Controller.

End of Travel (EOT) Switches

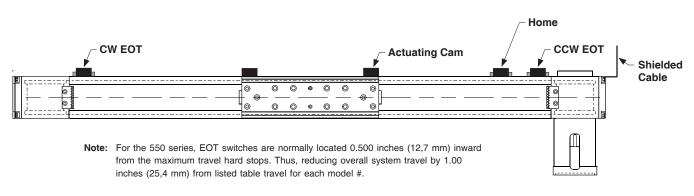
End of travel (EOT) switches can be utilized by a motion controller to stop carriage motion, thereby preventing any damage to personnel, table carriage, or user mounted load if the extreme end of travel has been reached by the carriage. There are two EOT switches mounted to the side of the table, one on each end. The CCW switch is mounted at the motor mount end, while the CW switch is located at the opposite end of the table. *LINTECH* provides normally closed (NC) end of travel switches. This provides for a power-off fail safe system, where the position controller can detect broken wires. *It is highly recommended that any positioning table used with a position controller, should have end of travel switches installed for protection of personnel, table carriage, and user mounted load.*

Home Switch

The home switch can be utilized by a motion controller as a known fixed mechanical location on the positioning table. The switch is located between the EOT switches, near the motor mount end, and is a normally open (NO) switch.

Switch Locations

The following diagram shows the locations of the switches when ordered from *LINTECH*.



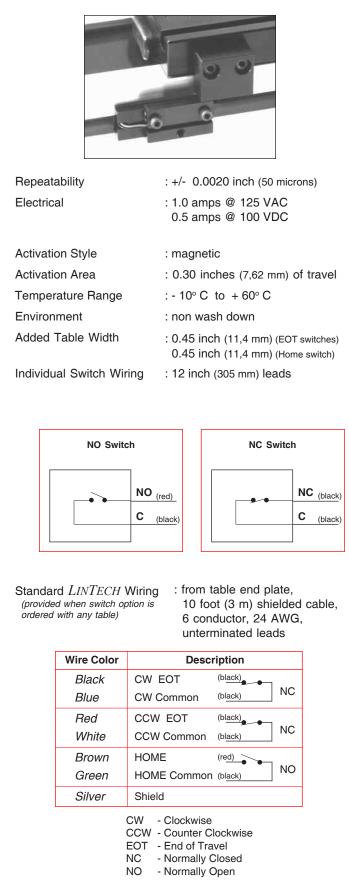
Note: Each switch can be located anywhere along the T-slots, which run on both sides of the table.

Switch Type	Cost	Repeatability inches (microns)	Actuated	Power Supply Required	Activation Area inches (mm)	Comments
reed	least expensive	+/- 0.0020 (50)	magnetic	No	0.30 (7,62)	for non-contact & low repeatable applications
hall effect	medium priced	+/- 0.0002 (5)	magnetic	Yes	0.32 (8,13)	for non-contact and wash down applications
proximity	most expensive	+/- 0.0002 (5)	non-magnetic	Yes	1.75 (44,45)	for non-contact, high speed, & wash down applications

Note: The repeatability of any switch is dependent upon several factors: carriage speed, accel rate, load weight, switch style, and the position controller. *L*IN*T*ECH's ratings are based upon a carriage speed of 0.5 inches/sec (12.7 mm/sec) and a no load condition.

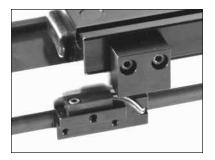
End of Travel (EOT) Switches & Home Switch

Non-Contact Reed Switches

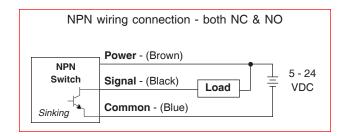


End of Travel (EOT) Switches & Home Switch

Non-Contact Hall Effect Switches



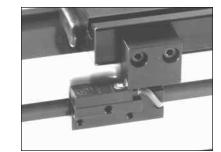
: +/- 0.0002 inch (5 microns)
: 5 - 24 VDC 15 mA - power input 25 mA max - signal
: magnetic
: 0.32 inches (8,13 mm) of travel
: - 10° C to + 60° C
: wash down
: 0.45 inch (11,4 mm) (EOT switches) 0.45 inch (11,4 mm) (Home switch)
: 12 inch (305 mm) leads



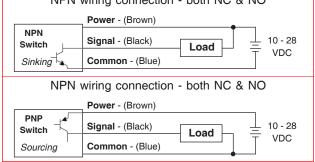
Standard *LINTECH* Wiring (provided when switch option is ordered with any table) : from table end plate, 10 foot (3 m) shielded cable; 9 conductor, 24 AWG, unterminated leads

Wire Color	Description							
Brown	CW Power	(brown)	1	1				
Black	CW EOT	(black)	switch	NC				
Blue	CW Common	(blue)						
Red	CCW Power	(brown)	1	1				
White	CCW EOT	(black)	switch	NC				
Green	CCW Common	(blue)						
Orange	Home Power	(brown)	-[1				
Yellow	Home	(black)	switch	NO				
Grey	Home Common	(blue)						
Silver	Shield							

Non-Contact Proximity Switches



Repeatability	: +/- 0.0002 inch (5 microns)					
Electrical	: 10 - 28 VDC 15 mA - power input 100 mA max - signal					
Actuation Style	: non-magnetic cam					
Activation Area	: 1.75 inches (44,45 mm) of trave					
Temperature Range	: - 25° C to + 75° C					
Environment	: IEC IP67 wash down					
Added Table Width	: 0.45 inch (11,4 mm) (EOT switches) 0.45 inch (11,4 mm) (Home switch)					
Individual Switch Wiring	: 6.5 foot (2 m) cable for NPN : 3.3 foot (1 m) cable for PNP					
NPN wiring connection - both NC & NO						

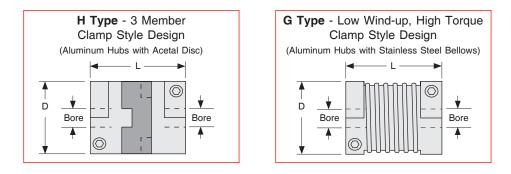


Standard *LINTECH* Wiring (provided when switch option is ordered with any table) : from table end plate, 10 foot (3 m) shielded cable; 9 conductor, 24 AWG, unterminated leads

Wire Color	Description					
Brown	CW Power	(brown)	1]		
Black	CW EOT	(black)	switch	NC		
Blue	CW Common	(blue)				
Red	CCW Power	(brown)		1		
White	CCW EOT	(black)	switch	NC		
Green	CCW Common	(blue)	-			
Orange	Home Power	(brown)	4	1		
Yellow	Home	(black)	switch	NO		
Grey	Home Common	(blue)				
Silver	Shield					

Motor Couplings

LINTECH provides three different types of couplings that can be used to mount a motor to a positioning table. These couplings compensate for misalignment between the motor shaft & belt drive shaft extension. This provides for trouble-free operation as long as certain precautions are taken. The connected motor output torque should never exceed the coupling maximum torque capacity. Larger capacity couplings may be required for applications having high accelerations, large back driving loads, high torque output motors, or servo motors.



Model	D	L		Bo	re Diam	eters	;		Weight	Inertia	Wind-up	Max Torque
Number	inches (mm)	inches (mm)	Table	Motor		mum (mm)		imum (mm)	ounces (grams)	oz-in² (g-cm²)	arc-sec/oz-in (deg/N-m)	oz-in (N-m)
H197-018-aaa	1.97 (50,0)	2.35 (59,7)	018	aaa	.375	10	.750	20	7.6 (215)	3.69 (674)	1.1 (0,043)	3,600 (25,4)
H225-018-aaa	2.25 (57,2)	3.07 (78,0)	018	aaa	.500	12	1.000	24	13.1 (371)	8.29 (1516)	0.6 (0,024)	5,300 (37,4)
G177-018-aaa	1.77 (45,0)	2.48 (63,0)	018	aaa	.375	10	.750	20	7.1 (200)	2.78 (508)	0.2 (0,008)	4,250 (30,0)
G220-018-aaa	2.20 (56,0)	2.68 (68,0)	018	aaa	.500	12	1.000	24	10.6 (300)	6.41 (1172)	0.04 (0,002)	7,100 (50,0)
G260-018-aaa ⁽¹⁾	2.60 (66,0)	3.07 (78,0)	018	aaa	.625	16	1.000	24	21.2 (600)	17.91 (3276)	0.03 (0,001)	9,600 (68,0)
Possible values for aaa	500 = 625 =	.375 inch .500 inch .625 inch .750 inch	99	9 = 1.000) inch		012 = 12 014 = 14	0 mm 2 mm 4 mm 6 mm	019 020	= 18 mn = 19 mn = 20 mn = 24 mn	n n	

Footnotes:

(1) This coupling option can not be used with the optional NEMA 34 & 42 motor mounts because its diameter is too large. Custom motor mounts can be provided upon request. See page K-25 for maximum coupling diameter and length specifications for use with the optional NEMA 34 & 42 motor mounts.

Motor Couplings

Coupling	Cost	Torque Capacity	Wind-up	Suggested Motor	Comments
Н Туре	less expensive	medium	medium	stepper or servo	use for high accels & for starting & stopping large inertia loads
G Туре	more expensive	high	the least	servo	use for very high torque requirements & very high servo accelerations

Specification	550 Series NEMA 34 & 42 bracket inches (mm)					
Shaft extension diameter at motor mount end	0.709 (18,0)					
Maximum coupling diameter	2.300 (58,42)					
Maximum coupling length	3.100 (78,74)					
Note: Custom brackets available upon request.						

Coupling Part Numbers

C293	H197-018-375	C359	H225-018-500	C573	G177-018-375	C639	G220-018-500	C684	G260-018-625
C294	H197-018-500	C360	H225-018-625	C574	G177-018-500	C640	G220-018-625	C685	G260-018-750
C295	H197-018-625	C361	H225-018-750	C575	G177-018-625	C641	G220-018-750	C686	G260-018-999
C296	H197-018-750	C362	H225-018-999	C576	G177-018-750	C642	G220-018-999	C687	G260-018-016
C297	H197-018-010	C363	H225-018-012	C577	G177-018-010	C643	G220-018-012	C688	G260-018-018
C298	H197-018-012	C364	H225-018-014	C578	G177-018-012	C644	G220-018-014	C689	G260-018-019
C299	H197-018-014	C365	H225-018-016	C579	G177-018-014	C645	G220-018-016	C690	G260-018-020
C300	H197-018-016	C366	H225-018-018	C580	G177-018-016	C646	G220-018-018	C691	G260-018-024
C301	H197-018-018	C367	H225-018-019	C581	G177-018-018	C647	G220-018-019		
C302	H197-018-019	C368	H225-018-020	C582	G177-018-019	C648	G220-018-020		
C303	H197-018-020	C369	H225-018-024	C583	G177-018-020	C649	G220-018-024		

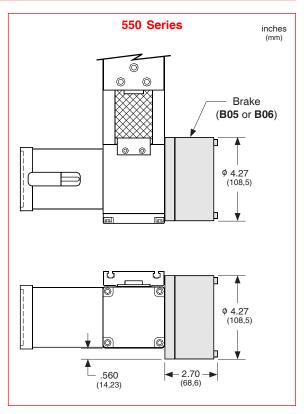
Power-off Electric Brakes

For vertical table applications, or for those applications requiring the load to be locked securely in place, an electric brake may be mounted to the positioning table. The 550 series will have the brake mounted to the "Thru Drive Shaft" option. With proper wiring from a control system, this power-off friction brake can ensure that the carriage is firmly held in place, when no electric power is applied to the brake. When power is applied to the brake, the brake is opened or "released".

For proper emergency braking of the 550 series table, this electric brake needs to be interfaced to a position controller or relay network. LINTECH also provides 24 & 90 VDC power supplies which can be used to power the brakes.

Brakes

Model	Holding Force	Excitation Voltage	Current	Weight
Number	in-lbs (N-m)	volts	amps	lbs (kg)
B05	180 (20,3)	24 VDC	1.136	4.8 (2,18)
B06	180 (20,3)	90 VDC	0.287	4.8 (2,18)



Note: This power-off electric brake MUST NOT be engaged when the positioning table is in motion. Moving the table with the brake applied could damage the brake and the positioning table. Also, continuous use of this brake to stop a table (load) that is in motion could damage the brake and the positioning table. Dynamic braking of a positioning table should be done by the motor and not the brake.

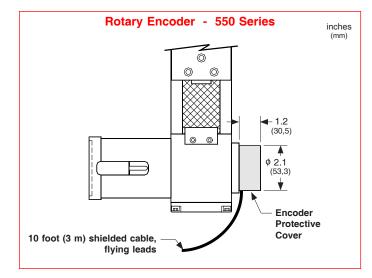
Power Supplies

Model		DC Out	put	AC Input			
Number	volts	amps	style	volts	amps	Hz	
41970	5	3.0	regulated	120 / 240	0.8 / 0.4	47-63	
37488	24	1.2	regulated	120 / 240	0.8 / 0.4	47-63	
37489	90	0.8	unregulated	120	1.0	50/60	
37490	90	0.8	unregulated	240	0.5	50/60	

Options

Rotary Incremental Encoders

Shaftless, incremental, optical rotary encoders can be mounted to the "Thru Drive Shaft" option on the 550 series positioning tables. These encoders provide positional feedback to either a motion controller, or a digital position display.



Wire Color	Description
White	Channel A ⁺ (or A)
Blue	Channel A ⁻ (or \overline{A})
Green	Channel B ⁺ (or B)
Orange	Channel B ⁻ (or \overline{B})
White/Black	Channel Z ⁺ (or Z)
Red/Black	Channel Z ⁻ (or \overline{Z})
Black	Common
Red	+ 5 vdc (+/- 5%)

Specification	ROTARY ENCODERS					
	E01	E02	E03			
Line Count	500 lines/rev	1000 lines/rev	1270 lines/rev			
Pre Quadrature Resolution	0.002 revs/pulse	0.001 revs/pulse	0.00079 revs/pulse			
Post Quadrature Resolution	0.0005 revs/pulse	0,00025 revs/pulse	0.00019 revs/pulse			
Maximum Speed		50 revs/sec				
Maximum Accel	40 revs/sec ²					
Excitation Power	+ 5 VDC @ 125 ma					
Operating Temperature	32º F	to 140° F (0° C to 6	0° C)			
Humidity	209	% to 80% non condens	sing			
Shock	10) G's for 11 msec duration	on			
Weight		0.7 lbs (0,283 kg)				
Cable Length	10 ft (3 m), unterminated 26 gauge leads					
Zero Reference Output	Once per revolution					
Outputs	TTL square wave; Two channel (A+ & B+); Differential (A- & B-); Line Driver					

Notes