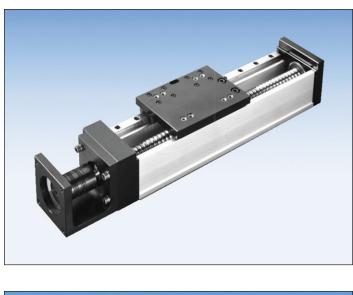
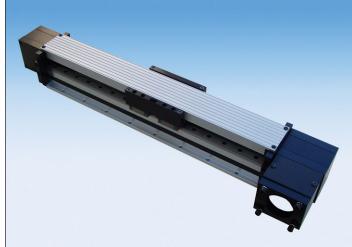
130 &140 Series Positioning Tables

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Single or Multiple Axis

LINTECH's 130 series positioning tables offer precision performance and design flexibility for use in a wide variety of Motion Control applications.

- Welding
- Test Stands
- Part Insertion
- Laser Positioning
- Liquid Dispensing
- Semiconductor Processing

Quality Construction

LINTECH's 130 series tables are designed to maximize performance while minimizing physical size and cost. These tables use a low friction, preloaded, recirculating linear ball bearing system, which rides on a single precision ground linear rail. The single linear rail is mounted to a precision machined aluminum base, which offers a rigid support over the entire travel of the table's carriage. The load is mounted to a precision machined aluminum carriage, which has threaded stainless steel inserts for high strength and wear life. There are 30 different acme & ball screw options, that offer high efficiencies and long life at an economical price. These tables are designed to allow for numerous options. They include EOT & Home switches, linear & rotary encoders, power-off electric brakes, motor wrap packages and versatile mounting brackets for multiple axis applications.

Motor Adapter Brackets

NEMA 23, NEMA 34, or any metric mount motor can be mounted to a 130 series positioning table with the use of adapter brackets.

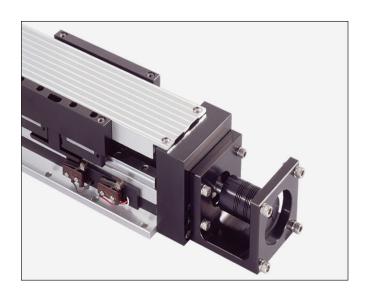
Turcite Nut With Rolled Ball Screw

This solid polymer nut has no rolling elements in it, and performs very similar to an acme nut. It can provide smoother motion & less audible noise than most ball nuts, and is ideal for corrosive & vertical applications.

Other

The 130 series tables can accommodate chrome plated linear bearings, rails, & screws for corrosive environment applications, power-off electric brakes for load locking applications, motor wrap packages for space limited applications, and a hand crank for manually operated applications.

Specifications subject to change without notice



- Gluing Pick & Place
- Part Scanning
- Inspection Stations
- General Automation

LINTECH[®]

An assortment of acme screws and ball screws can be installed in the 130 series tables, providing solutions to load back driving, high duty cycle, high speed, extreme smoothness, and sensitive positioning applications.

Acme Screws & Ball Screws

Available Options

Carriage Adapter Plates & Vertical Angle Brackets

Optional carriage adapter plates and vertical angle brackets can be mounted directly to the top of various LINTECH positioning tables, thus providing for easy multiple axis configurations.

Cover Plates

For operator protection, these tables can be fitted with aluminum cover plates. The entire length of the lead screw and linear bearing system will be covered.

End of Travel and Home Switches

The 130 series tables can be provided with end of travel (EOT) and home switches mounted and wired for each axis. Most position controllers can utilize the EOT switches to stop carriage motion when the extreme table travel has been reached in either direction. The home switch provides a known mechanical location on the table.

Linear and Rotary Encoders

Incremental encoders can be mounted to the table in order to provide positional data back to either a motion controller, or a digital display.

Standard Features - 130 Series

- Compact 2.875 inches (73 mm) wide by 2.375 inches (60 mm) tall
- Travel lengths from 2 inches (50 mm) to 60 inches (1520 mm)
- Threaded stainless steel inserts in carriage for load mounting
- □ 0° F to +185° F (-18° C to +85° C) operating temperature
- Recirculating linear ball bearing system
- Precision ground square rail design
- 1 rail, 1 or 2 bearing carriages



Specifications subject to change without notice

LINTECH[®]

Ordering Guide

	13	2 4 02 -	CP0 - 1 -	S114	M02 - C1	45 L01	- E00	- B(
Table Series								
Iumber of Bearing1 - 1 bearing per ca2 - 2 bearings per ca	arriage							
arriage Length								
ravel Length (see p 02 - 2 to 60 inches	ages B-6, B-8 & B-10)							
Cover Plate								
CP0 - no cover plates	CP1 - top cover plate only	CP2 - top & cover						
Carriage Inserts (see 1 - English mount								
Screw Options (see	pages B-14 to B-19) _							
Rolled ball screws S001500 x .500 S002500 x .500 S003500 x .500 S004500 x .500 S005625 x .200 S006625 x .200 S007625 x .200 S008625 x .200 S009625 x .200 S010625 x .200 S010625 x .200 S011625 x .000 S011625 x 1.000 S012625 x 1.000	0 NPL S114 0 PL S115 0 NPL(T) S116 0 PL(T) S117 0 PL(T) S117 0 NPL S118 0 PL S119 0 NPL(T) S120 0 PL(T) S121 0 NPL D121 0 NPL D121 0 PL D121 0 NPL NPL	on ball screws .625 x .200 NF .625 x .200 PL 16 x 5 NPL 16 x 5 PL 16 x 10 NPL 16 x 10 PL 16 x 16 NPL 16 x 16 PL	S213 625 S214 - 16 S215 - 16 Rolled acme 625 S300 625 S302 625	x .200 PL x .500 PL x 5 PL x 16 PL screws x .100 NP x .100 PL x .200 NP x .200 PL x 4 NPL				
/lotor Mount (see pa	nes B-7 B-9 B-11 B-4	2 & B-43)						
M00 - none M01 - hand crank	M02 - NEMA M03 - NEMA	23 mount (E) 23 mount (M) 34 mount (E)	M06 - NEMA M07 - NEMA	A 23 (RH) wra A 23 (LH) wra A 34 (RH) wra	p			
M99 - other	M05 - NEMA	34 mount (M)	M09 - NEMA	A 34 (LH) wra	p			
Coupling Options (see pages B-38 to B-39)						
C000 - none C999 - other	C020 to C024 - C C040 to C047 - C	100 C125 125 C145	to C129 - H100 to C154 - H131		to C406 - G100 to C434 - G126			
imit & Home Swite	ches (see pages B-35	to B-37)						
L00 - no switches L99 - other	EOT & home swite	Mechanical thes L01	Reed	Hall L07	Prox (NPN) L10	Prox (PNP)		
L99 - Other	EOT switches	only L02	L04 L05	L08	L11	L13 L14		
	home switch	only L03	L06	L09	L12	L15		Í
Encoder Options (s				(0500 l'	- (in th)	ath au]	
E00 - none E01 - rotary (500 lin		otary (1000 lines/re otary (1270 lines/re		ear (2500 line ear (125 lines	s/inch) E99 /mm)	- otner		
Power-off Brakes (s	ee page $R_{-1/1}$							
	B01 - 24 VDC		B99 - oth	ner				
				(E) - English In	terface (NPL) -	Non Prelo	aded
				(L	H) - Left Hand	(PL) -	Preloaded	
pecifications subject to change without n				A)	 Metric International 	. ,	Right Han Turcite Nu	



- Screw Drive -

Specifications

Load Ca	pacities	One	e (1) Be	aring Car	riage	Tw	o (2) Be	earing Car	riage
Dynamic Horizontal	2 million inches (50 km) of travel	100	lbs	(45	kg)	200	lbs	(90	kg)
Dynamic Horizontal	50 million inches (1270 km) of travel	34	lbs	(15	kg)	68	lbs	(30	kg)
Static Horizontal		200	lbs	(90	kg)	400	lbs	(180	kg)
Dynamic Roll Moment	2 million inches (50 km) of travel	8	ft-lbs	(11	N-m)	16	ft-lbs	(22	N-m)
Dynamic Roll Moment	50 million inches (1270 km) of travel	3	ft-lbs	(4	N-m)	5	ft-lbs	(7	N-m)
Static Roll Moment		14	ft-lbs	(19	N-m)	28	ft-lbs	(38	N-m)
Dyn. Pitch & Yaw Moment	2 million inches (50 km) of travel	4	ft-lbs	(5,4	N-m)	15	ft-lbs	(20	N-m)
Dyn. Pitch & Yaw Moment	50 million inches (1270 km) of travel	1	ft-lbs	(1,9	N-m)	5	ft-lbs	(7	N-m)
Static Pitch & Yaw Moment		8	ft-lbs	(10	N-m)	30	ft-lbs	(40	N-m)
Each Bearing Dyn. Capacity	2 million inches (50 km) of travel	100	lbs	(45	kg)	100	lbs	(45	kg)
Each Bearing Dyn. Capacity	50 million inches (1270 km) of travel	34	lbs	(15	kg)	34	lbs	(15	kg)
Each Bearing Static Load C	apacity	200	lbs	(90	kg)	200	lbs	(90	kg)
Thrust Force Capacity	10 million screw revolutions	665	lbs	(302	kg)	665	lbs	(302	kg)
Thrust Force Capacity	500 million screw revolutions	180	lbs	(82	kg)	180	lbs	(82	kg)
Maximum Acceleration		50	in/sec ²	(1,3 r	m/sec²)	150	in/sec ²	(3,8 r	n/sec²)
d ₂ Center to center distance (space	cing) of each bearing on a single rail			-		2.0	088 in	(53,0	mm)
\mathbf{d}_{r} CP0 version Center distance of the	bearing to top of carriage plate surface	0.7	50 in	(19,1	mm)	0.7	750 in	(19,1	mm)
$\mathbf{d}_{\mathbf{r}}^{}$ CP1 version Center distance of the	bearing to top of carriage plate surface	1.3	75 in	(34,9	mm)	1.3	375 in	(34,9	mm)

Other	For One (1) & Two (2) Bearing Carriages
Table Material	Base, Carriage, End Plates, & Cover Plate option - 6061 anodized aluminum
Linear Rail Material	Stainless Steel
Screw Material (see pages B-14 to B-19)	Acme Screw - Stainless Steel
Screw Material (see pages B-14 to B-19)	Rolled Ball, Precision Ball, & Ground Ball - Case Hardened Steel
Straightness	< 0.00013 in/in (< 3,30 microns/25mm)
Flatness	< 0.00013 in/in (< 3,30 microns/25mm)
Orthogonality (multi-axis systems)	< 30 arc-seconds
Friction Coefficient	< 0.01
Motor Mount	NEMA 23 & 34 Mounts, Metric Mounts, Motor Wraps, and Hand Crank Option
Coupling	Three (3) different styles available

Dimensions & Specifications

- Without Cover Plates -

Model Number	Travel Length inches	inc	mensions hes m)		Dimens iches (mm)	sions	Screw Length inches	Table ⁽ Weight Ibs
	(mm)	А	В	С	E	М	(mm)	(kg)
13x402-CP0	2 (50)	6.0 (152,4)	9.875 (250,8)	0.188 (4,8)	3	8	9.25 (235)	4.8 (2,2)
13x404-CP0	4 (100)	8.0 (203,2)	11.875 (301,6)	1.188 (30,2)	3	8	11.25 (286)	5.3 (2,4)
13x406-CP0	6 (150)	10.0 (254,0)	13.875 (352,4)	0.313 (8,0)	5	12	13.25 (337)	5.8 (2,6)
13x408-CP0	8 (200)	12.0 (304,8)	15.875 (403,2)	1.313 (33,4)	5	12	15.25 (387)	6.3 (2,9)
13x412-CP0	12 (300)	16.0 (406,4)	19.875 (504,8)	1.438 (36,5)	7	16	19.25 (489)	7.3 (3,3)
13x416-CP0	16 (405)	20.0 (508,0)	23.875 (606,4)	1.563 (39,7)	9	20	23.25 (591)	8.3 (3,8)
13x420-CP0	20 (505)	24.0 (609,6)	27.875 (708,0)	1.688 (42,9)	11	24	27.25 (692)	9.3 (4,2)
13x424-CP0	24 (605)	28.0 (711.2)	31.875 (809,6)	1.813 (46,1)	13	28	31.25 (794)	10.3 (4,7)
13x430-CP0	30 (760)	34.0 (863,6)	37.875 (962,0)	1.063 (27,0)	17	36	37.25 (946)	11.8 (5,4)
13x436-CP0	36 (910)	40.0 (1016,0)	43.875 (1114,4)	0.313 (8,0)	21	44	43.25 (1099)	13.3 (6,0)
13x442-CP0	42 (1060)	46.0 (1168,4)	49.875 (1266,8)	1.438 (36,5)	23	48	49.25 (1251)	14.8 (6,7)
13x448-CP0	48 (1215)	52.0 (1320,8)	55.875 (1419,2)	0.688 (17,5)	27	56	55.25 (1403)	16.3 (7,4)
13x454-CP0	54 (1370)	58.0 (1473,2)	61.875 (1571,6)	1.813 (46,1)	29	60	61.25 (1556)	17.8 (8,1)
13x460-CP0	60 (1520)	64.0 (1625,6)	67.875 (1724,0)	1.063 (27,0)	33	68	67.25 (1708)	19.3 (8,8)

— x = 1; Carriage has 1 bearing; Carriage weight = 1.1 lbs. (0,50 kg)

- x = 2; Carriage has 2 bearings; Carriage weight = 1.2 lbs. (0,55 kg)

Footnotes:

(1) Weight shown is with a 0.625 inch (16 mm) diameter screw, a 1 bearing carriage [1.1 lbs (0,55 kg)], a NEMA 23 motor mount [0.34 lbs (0,16 kg)], and a C100 style [0.09 lbs (0,04 kg)] coupling. When using a 0.500 inch diameter screw subtract 0.022 lbs per inch (0,00039 kg per mm) of screw length for a given model number. When using a 2 bearing carriage add 0.1 lbs (0,05 kg) to each value.

Specifications subject to change without notice

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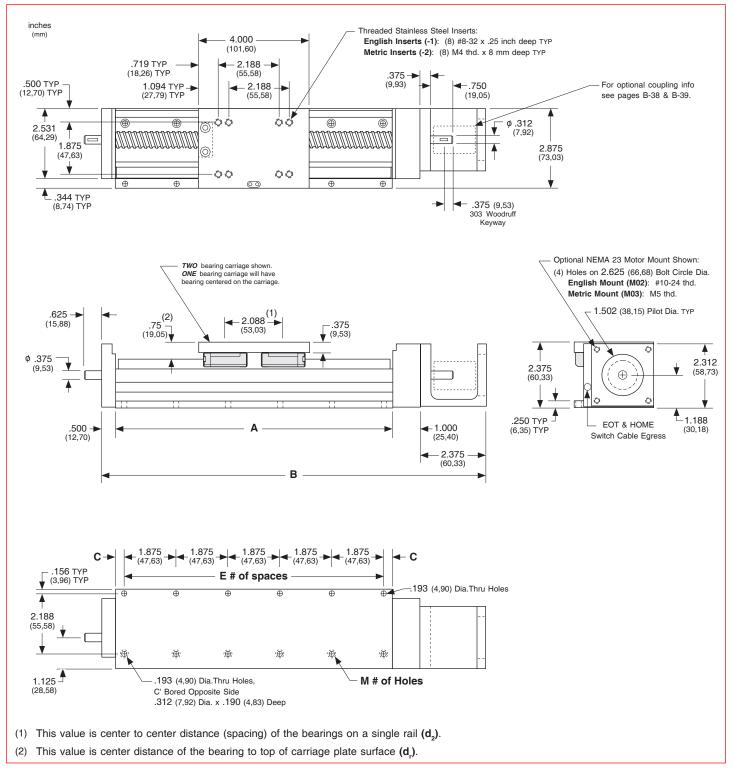
Technical Reference

- Screw Drive -

130-CP0 Series

Dimensions

- Without Cover Plates -



Note: Any 130 series table can be mounted on top of a second 130 series table, in order to create X-Y multiple axis configurations. *LINTECH* recommends that a 2 bearing carriage be used for the bottom axis, and that the top axis should never extend out more than 18 inches in either direction, from the bottom axis carriage edge, without the use of a support bearing system on the outer edges of the top axis. The 130-CP1, 130-CP2 or 140 series requires a **Carriage Adapter Plate** option. The carriage's threaded stainless steel insert hole pattern exactly matches the base mounting hole pattern on each table, therefore no adapter bracket or extra machining is required. However a precision square tool, or micrometer depth gauge, is required in order to obtain an orthogonality between the two tables of < 30 arc-seconds. The table base, carriage top & carriage sides are all precision machined. *LINTECH*'s 100 or 120 series tables should be used for the bottom axis in a multiple axes application for better system rigidity, performance, and life.

Dimensions & Specifications

- With Top Cover Plate Only -

Model Number	Travel Length inches	inc	mensions hes m)		Dimens iches (mm)	sions	Screw Length inches	Table ^{(†} Weight Ibs
	(mm)	A B		С	C E M		(mm)	(kg)
13x402-CP1	2 (50)	6.0 (152,4)	9.875 (250,8)	0.188 (4,8)	3	8	9.25 (235)	5.5 (2,5)
13x404-CP1	4 (100)	8.0 (203,2)	11.875 (301,6)	1.188 (30,2)	3	8	11.25 (286)	6.2 (2,8)
13x406-CP1	6 (150)	10.0 (254,0)	13.875 (352,4)	0.313 (8,0)	5	12	13.25 (337)	6.8 (3,1)
13x408-CP1	8 (200)	12.0 (304,8)	15.875 (403,2)	1.313 (33,4)	5	12	15.25 (387)	7.4 (3,4)
13x412-CP1	12 (300)	16.0 (406,4)	19.875 (504,8)	1.438 (36,5)	7	16	19.25 (489)	8.8 (4,0)
13x416-CP1	16 (405)	20.0 (508,0)	23.875 (606,4)	1.563 (39,7)	9	20	23.25 (591)	10.0 (4,5)
13x420-CP1	20 (505)	24.0 (609,6)	27.875 (708,0)	1.688 (42,9)	11	24	27.25 (692)	11.3 (5,1)
13x424-CP1	24 (605)	28.0 (711.2)	31.875 (809,6)	1.813 (46,1)	13	28	31.25 (794)	12.6 (5,7)
13x430-CP1	30 (760)	34.0 (863,6)	37.875 (962,0)	1.063 (27,0)	17	36	37.25 (946)	14.6 (6,6)
13x436-CP1	36 (910)	40.0 (1016,0)	43.875 (1114,4)	0.313 (8,0)	21	44	43.25 (1099)	16.5 (7,5)
13x442-CP1	42 (1060)	46.0 (1168,4)	49.875 (1266,8)	1.438 (36,5)	23	48	49.25 (1251)	18.4 (8,4)
13x448-CP1	48 (1215)	52.0 (1320,8)	55.875 (1419,2)	0.688 (17,5)	27	56	55.25 (1403)	20.4 (9,3)
13x454-CP1	54 (1370)	58.0 (1473,2)	61.875 (1571,6)	1.813 (46,1)	29	60	61.25 (1556)	22.3 (10,1)
13x460-CP1	60 (1520)	64.0 (1625,6)	67.875 (1724,0)	1.063 (27,0)	33	68	67.25 (1708)	24.3 (11,0)

x = 1; Carriage has 1 bearing; Carriage weight = 1.4 lbs. (0,64 kg)

- x = 2; Carriage has 2 bearings; Carriage weight = 1.5 lbs. (0,68 kg)

Footnotes:

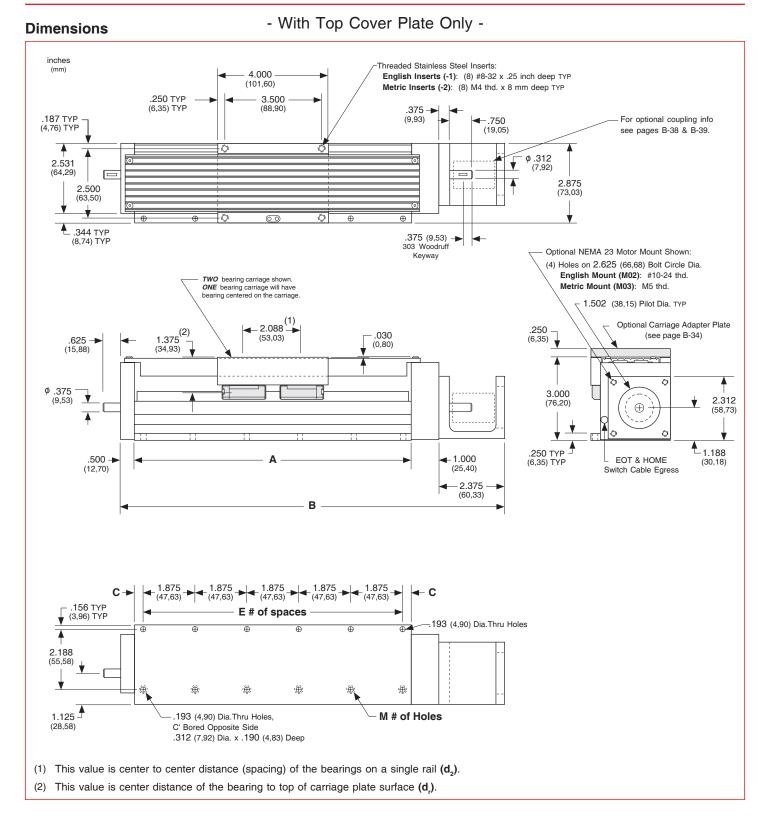
(1) Weight shown is with a 0.625 inch (16 mm) diameter screw, a 1 bearing carriage [1.1 lbs (0,55 kg)], a NEMA 23 motor mount [0.34 lbs (0,16 kg)], and a C100 style [0.09 lbs (0,04 kg)] coupling. When using a 0.500 inch diameter screw subtract 0.022 lbs per inch (0,00039 kg per mm) of screw length for a given model number. When using a 2 bearing carriage add 0.1 lbs (0,05 kg) to each value.



Technical Reference

- Screw Drive -

130-CP1 Series



Note: Any 130 series table can be mounted on top of a second 130 series table, in order to create X-Y multiple axis configurations. *LINTECH* recommends that a 2 bearing carriage be used for the bottom axis, and that the top axis should never extend out more than 18 inches in either direction, from the bottom axis carriage edge, without the use of a support bearing system on the outer edges of the top axis. The 130-CP1, 130-CP2 or 140 series requires a **Carriage Adapter Plate** option. The carriage's threaded stainless steel insert hole pattern exactly matches the base mounting hole pattern on each table, therefore no adapter bracket or extra machining is required. However a precision square tool, or micrometer depth gauge, is required in order to obtain an orthogonality between the two tables of < 30 arc-seconds. The table base, carriage top & carriage sides are all precision machined. *LINTECH*'s 100 or 120 series tables should be used for the bottom axis in a multiple axes application for better system rigidity, performance, and life.

Dimensions & Specifications

- With Top & Side Cover Plates -

Model Number	Travel Length inches	incl	mensions hes m)		Dimens iches (mm)	sions	Screw Length inches	Table ⁽¹⁾ Weight Ibs	
	(mm)	А	В	С	Е	М	(mm)	(kg)	
13x402-CP2	2 (50)	6.0 (152,4)	9.875 (250,8)	0.188 (4,8)	3	8	9.25 (235)	5.7 (2,58)	
13x404-CP2	4 (100)	8.0 (203,2)	11.875 (301,6)	1.188 (30,2)	3	8	11.25 (286)	6.4 (2,90)	
13x406-CP2	6 (150)	10.0 (254,0)	13.875 (352,4)	0.313 (8,0)	5	12	13.25 (337)	7.0 (3,17)	
13x408-CP2	8 (200)	12.0 (304,8)	15.875 (403,2)	1.313 (33,4)	5	12	15.25 (387)	7.6 (3,45)	
13x412-CP2	12 (300)	16.0 (406,4)	19.875 (504,8)	1.438 (36,5)	7	16	19.25 (489)	9.1 (4,13)	
13x416-CP2	16 (405)	20.0 (508,0)	23.875 (606,4)	1.563 (39,7)	9	20	23.25 (591)	10.4 (4,72)	
13x420-CP2	20 (505)	24.0 (609,6)	27.875 (708,0)	1.688 (42,9)	11	24	27.25 (692)	11.7 (5,31)	
13x424-CP2	24 (605)	28.0 (711.2)	31.875 (809,6)	1.813 (46,1)	13	28	31.25 (794)	13.1 (5,94)	
13x430-CP2	30 (760)	34.0 (863,6)	37.875 (962,0)	1.063 (27,0)	17	36	37.25 (946)	15.1 (6,85)	
13x436-CP2	36 (910)	40.0 (1016,0)	43.875 (1114,4)	0.313 (8,0)	21	44	43.25 (1099)	17.1 (7,76)	
13x442-CP2	42 (1060)	46.0 (1168,4)	49.875 (1266,8)	1.438 (36,5)	23	48	49.25 (1251)	19.1 (8,66)	
13x448-CP2	48 (1215)	52.0 (1320,8)	55.875 (1419,2)	0.688 (17,5)	27	56	55.25 (1403)	21.2 (9,62)	
13x454-CP2	54 (1370)	58.0 (1473,2)	61.875 (1571,6)	1.813 (46,1)	29	60	61.25 (1556)	23.2 (10,52)	
13x460-CP2	60 (1520)	64.0 (1625,6)	67.875 (1724,0)	1.063 (27,0)	33	68	67.25 (1708)	25.3 (11,47)	

x = 1; Carriage has 1 bearing; Carriage weight = 1.4 lbs. (0,64 kg)

- x = 2; Carriage has 2 bearings; Carriage weight = 1.5 lbs. (0,68 kg)

Footnotes:

(1) Weight shown is with a 0.625 inch (16 mm) diameter screw, a 1 bearing carriage [1.1 lbs (0,55 kg)], a NEMA 23 motor mount [0.34 lbs (0,16 kg)], and a C100 style [0.09 lbs (0,04 kg)] coupling. When using a 0.500 inch diameter screw subtract 0.022 lbs per inch (0,00039 kg per mm) of screw length for a given model number. When using a 2 bearing carriage add 0.1 lbs (0,05 kg) to each value.



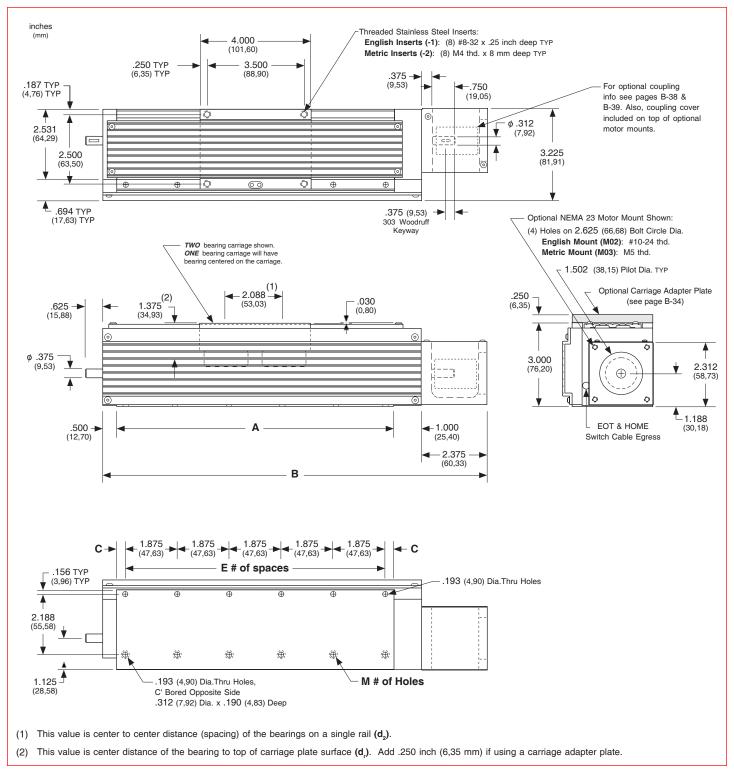
Technical Reference

- Screw Drive -

130-CP2 Series



- With Top & Side Cover Plates -



Note: Any 130 series table can be mounted on top of a second 130 series table, in order to create X-Y multiple axis configurations. *LINTECH* recommends that a 2 bearing carriage be used for the bottom axis, and that the top axis should never extend out more than 18 inches in either direction, from the bottom axis carriage edge, without the use of a support bearing system on the outer edges of the top axis. The 130-CP1, 130-CP2 or 140 series requires a **Carriage Adapter Plate** option. The carriage's threaded stainless steel insert hole pattern exactly matches the base mounting hole pattern on each table, therefore no adapter bracket or extra machining is required. However a precision square tool, or micrometer depth gauge, is required in order to obtain an orthogonality between the two tables of < 30 arc-seconds. The table base, carriage top & carriage sides are all precision machined. *LINTECH*'s 100 or 120 series tables should be used for the bottom axis in a multiple axes application for better system rigidity, performance, and life.

F =

Thrust Capacity (axial load)

R

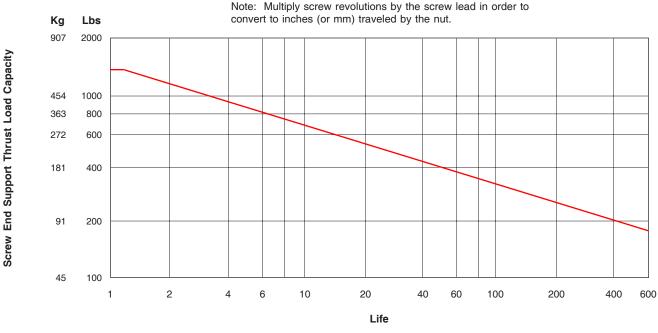
The life of the screw end support bearings can be estimated by evaluating the applied axial (thrust) load. The applied load "as seen by the bearings" depends upon the table orientation. Typically, the extra force acting upon the bearings during the acceleration interval is offset by a reduction in force during the deceleration interval. Therefore, evaluating the life of the bearings at a constant speed is adequate. The life of the screw end support bearings may not be the limiting element for a given application. See page B-13 for load/life capacity of acme and ball screw nuts.

Horizontal ApplicationVertical Application
$$F = (W \times \mu) + E$$
 $F = W + E$

$$L = \left[\frac{R}{F \times S}\right]^3 \times B$$

- В 2 (for millions of revolutions) =
- Ε externally applied extra forces =
- F = applied axial load (as seen by the bearings)
- L calculated life (millions of revolutions) =
 - = dynamic load capacity of bearings at 2 million screw revolutions (see below)
- S = safety factor (1 to 8)
- user mounted load weight to carriage W =
 - coefficient of friction for linear bearing system (0.01) =

Screw End Supports			Number of Screw Revolutions millions of screw revolutions									
End Sup	pons	Static	1	2	10	50	100	500				
Thrust Capacity	lbs (kg)	1,355 (615)	1,355 (615)	1,145 (519)	665 (302)	395 (179)	305 (138)	180 (82)				



millions of screw revolutions

Specifications subject to change without notice

B-12



Technical Reference

Screw Travel Life

Ε

F

L

The life of an acme or ball screw can be estimated by evaluating the load applied to the nut. The applied load "as seen by the screw nut" depends upon the table orientation. Typically, the extra force acting upon the screw nut during the acceleration interval is offset by a reduction in force during the deceleration interval. Therefore, evaluating the life of the screw nut at a constant speed is adequate. The life of the screw nut may not be the limiting element for a given application. See page B-12 for load/life capacity of the screw end support bearings.

Horizontal Application	Vertical Application
$\mathbf{F} = (\mathbf{W} \times \boldsymbol{\mu}) + \mathbf{E}$	F = W + E

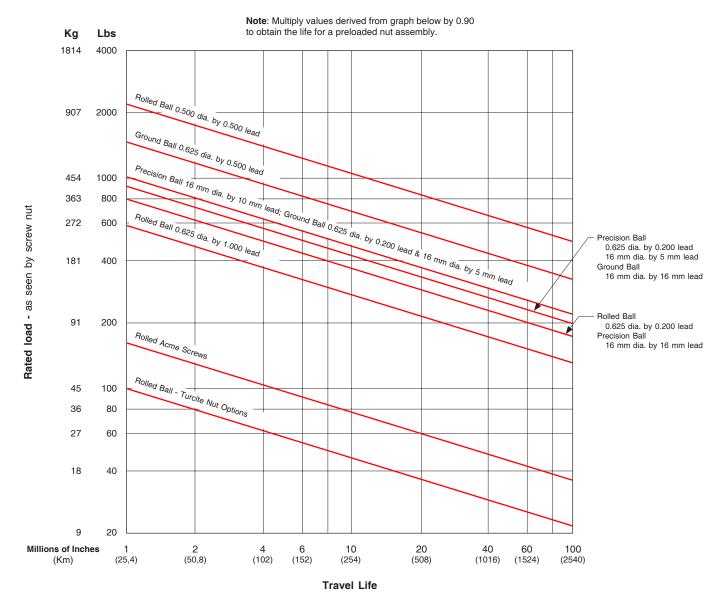
 $L = \left[\frac{R}{F \times S} \right]^{3} \times B$

B = either 1 (for millions of inches) or 25 (for Km)

- = externally applied extra forces
- = applied axial load (as seen by screw nut)
- = calculated travel life (millions of inches or Km)

R = rated dynamic load capacity of screw nut at 1 million inches of travel or 25 Km (see pages B-22 to B-25)

- S = safety factor (1 to 8)
- W = user mounted load weight to carriage
- μ = coefficient of friction for linear bearing system (0.01)



Acme screws use a turcite (polymer), or bronze nut. The nut threads ride in the matching acme screw threads, much like the ordinary nut and bolt system. This produces a higher friction (lower efficiency) system than a ball screw assembly, since there are no rolling elements between the nut and the acme screw threads. For applications requiring low speeds, noise and duty cycles, an acme screw works fine. Also, an acme screw is a good choice for most vertical applications, as it typically prevents back driving of the attached load.

Ball screws are the screw of choice for high duty cycle, high speed, and long life applications. The 130 series tables can be fitted with an assortment of ball screws. The ball screw nut uses one or more circuits of recirculating steel balls which roll between the nut and ball screw grooves, providing an efficient low friction system. Using a higher lead ball screw (for example a 0.500 inch lead instead of a 0.200 inch lead) will offer greater carriage speed for applications requiring rapid traverse, or fast, short moves. Low wear and long life are key features of a ball screw system.

LINTECH provides three different ball screw configurations. The rolled ball screw system utilizes a tapped nut with a standard accuracy grade rolled screw. The precision ball screw system utilizes a ground nut with a higher accuracy grade rolled screw. The ground ball screw system utilizes a ground nut with a high accuracy precision ground screw.

Some screws are available with preloaded nuts. The preloaded nut assembly offers high *bidirectional* repeatability by eliminating backlash.

Consideration	Acme Screw		Ball Screws		Comments
Consideration	Achie Screw	Rolled	Precision	Ground	Connients
Audible noise	least audible noise	most audible noise	less audible noise than rolled screw	less audible noise than precision screw	<i>Acme</i> : no rolling elements provide for quiet operation. <i>Ball</i> : recirculating balls in nut assembly transmit audible noise during motion; due to more accurate machining procedures - precision & ground ball screws are quieter than rolled ball screws.
Back Driving Loads	may prevent back driving	can easily back drive a load	can easily back drive a load	can easily back drive a load	Acme : good for light loads & vertical applications. Ball : recirculating balls in nut assembly produce a low friction system; vertical applications may require a brake to hold the load when no power is applied to the motor.
Backlash non-preloaded nut	will increase with wear	constant	constant	constant	<i>Acme</i> : preloaded nut assembly eliminates backlash. <i>Ball</i> : preloaded nut assembly eliminates backlash.
Duty Cycle	low to medium (< 50 %)	high (100 %)	high (100 %)	high (100 %)	Acme : low duty cycle due to high sliding friction. Ball : high duty cycle due to recirculating balls in nut assembly; high efficiency & low friction system.
Life	shorter due to higher friction	long	long	long	Acme : mechanical wear related to duty cycle, load & speed. Ball : minimal wear if operated in proper environment, within load specifications, and periodically lubricated.
Relative - Cost	slightly more than rolled ball	least expensive	slightly more than rolled ball	most expensive	<i>Acme</i> : a little more expensive than the rolled ball screw. <i>Ball</i> : due to more accurate manufacturing procedures precision rolled & ground ball screws are more expensive.
Screw Efficiency	low 40 % -Acme 60 % -Turcite	high (90 %)	high (90 %)	high (90 %)	<i>Acme</i> : low efficiency due to high sliding friction. <i>Ball</i> : high efficiency due to recirculating balls in nut assembly - low friction system.
Smoothness	can be smooth	least smooth	medium smoothness	smoothest	<i>Acme</i> : due to friction can start/stop at very low speeds. <i>Ball</i> : smoothness is constant through a wide speed range; due to more accurate manufacturing procedures precision rolled & ground ball screws are smoother than rolled ball screws.
Speeds	low	high	high	high	Acme : high friction can causes excess heat & wear at high speeds. Ball : recirculating balls in nut provide for a high speed system due to low friction & high efficiency.



130 Se	eries			Мах		e Table Op /sec (mm/se	perating S	peed ⁽¹⁾		
Model	Travel					Screw				
Number	Length inches (mm)	0.500 dia. 0.500 lead	0.625 dia. 0.100 lead	0.625 dia. 0.200 lead	0.625 dia. 0.500 lead	0.625 dia. 1.000 lead	16 mm dia. 4 mm lead	16 mm dia. 5 mm lead	16 mm dia. 10 mm lead	16 mm dia. 16 mm lead
13x402	2	25.0	5.0	10.0	25.0	50.0	7.9	9.8	19.7	31.5
	(50)	(635)	(127)	(254)	(635)	(1270)	(201)	(249)	(500)	(800)
13x404	4	25.0	5.0	10.0	25.0	50.0	7.9	9.8	19.7	31.5
	(100)	(635)	(127)	(254)	(635)	(1270)	(201)	(249)	(500)	(800)
13x406	6	25.0	5.0	10.0	25.0	50.0	7.9	9.8	19.7	31.5
	(150)	(635)	(127)	(254)	(635)	(1270)	(201)	(249)	(500)	(800)
13x408	8	25.0	5.0	10.0	25.0	50.0	7.9	9.8	19.7	31.5
	(200)	(635)	(127)	(254)	(635)	(1270)	(201)	(249)	(500)	(800)
13x412	12	25.0	5.0	10.0	25.0	50.0	7.9	9.8	19.7	31.5
	(300)	(635)	(127)	(254)	(635)	(1270)	(201)	(249)	(500)	(800)
13x416	16	25.0	5.0	10.0	25.0	50.0	7.9	9.8	19.7	31.5
	(405)	(635)	(127)	(254)	(635)	(1270)	(201)	(249)	(500)	(800)
13x420	20	21.5	5.0	10.0	25.0	50.0	7.9	9.8	19.7	31.5
	(505)	(546)	(127)	(254)	(635)	(1270)	(201)	(249)	(500)	(800)
13x424	24	16.1	4.2	8.4	21.0	41.9	6.5	8.2	16.4	26.2
	(605)	(409)	(107)	(213)	(533)	(1064)	(165)	(208)	(416)	(665)
13x430	30	11.2	2.9	5.8	14.5	29.0	4.5	5.6	11.3	18.1
	(760)	(284)	(74)	(147)	(368)	(737)	(114)	(142)	(287)	(460)
13x436	36	8.2	2.1	4.2	10.6	21.3	3.3	4.1	8.3	13.3
	(910)	(208)	(53)	(107)	(269)	(541)	(84)	(104)	(211)	(338)
13x442	42	6.2	1.6	3.3	8.1	16.3	2.5	3.2	6.3	10.1
	(1060)	(157)	(41)	(81)	(206)	(414)	(63)	(81)	(160)	(257)
13x448	48	4.9	1.3	2.5	6.4	12.8	2.0	2.5	5.0	8.0
	(1215)	(124)	(33)	(63)	(162)	(325)	(51)	(63)	(127)	(203)
13x454	54	4.0	1.0	2.0	5.2	10.4	1.6	2.0	4.0	6.5
	(1370)	(102)	(25)	(51)	(132)	(264)	(41)	(51)	(102)	(165)
13x460	60	3.3	0.8	1.7	4.3	8.6	1.3	1.7	3.3	5.3
	(1520)	(84)	(20)	(43)	(109)	(218)	(33)	(43)	(84)	(135)

Footnotes:

(1) These listed speeds are a mechanical limitation. The maximum speed of a positioning table depends on the screw diameter, screw lead, screw length, and the screw end bearing support configuration. *LINTECH* uses a fixed-simple screw end bearing support configuration in its positioning tables. The correct motor & drive system needs to be selected in order to obtain the above maximum table speeds.

						ROLLED BA	LL SCREW	'S			
	SCREW	Dyn. ⁽¹⁾ Capacity	Static Capacity	Screw Efficiency	Breakaway Torque	Position Accuracy	Backlash	Unidirectional Repeatability	Bidirectional Repeatability		
		lbs (kg)	lbs (kg)	%	oz-in (N-m)	inch/ft (microns/300 mm)			inches (microns)		
dia. ead	Non-preloaded (S001)	2,200 (997)	13,350 (6055)	90	15 (0,11)		< 0.008 (203)		+ 0.0002 to - 0.0082 (5) (208)		
0.500 inch dia. 0.500 inch lead	(2) Preloaded (S002)	1,980 (898)	13,130 (5955)		30 (0,21)	< 0.003	0	+/- 0.0002 (5)	+ 0.0002 to - 0.0002 (5) (5)		
0.5	<i>Non-preloaded</i> Turcite Nut (S003)	100 (45)	800 (363)	60	25 (0,18)	(75)	< 0.008 (203)		+ 0.0002 to - 0.0082 (5) (208)		
	<i>Preloaded</i> Turcite Nut (S004)	90 (41)	800 (363)		40 (0,28)		0		+ 0.0002 <i>to</i> - 0.0002 (5) (5)		
dia. ead	Non-preloaded (S005)	800 (363)	6,150 (2790)	90 20 (0,14) < 0.003			< 0.008 (203)		+ 0.0002 to - 0.0082 (5) (208)		
0.625 inch dia. 0.200 inch lead	Preloaded (S006)	720 (326)	6,070 (2753)			0	+/- 0.0002	+ 0.0002 to - 0.0002 (5) (5)			
0.0	<i>Non-preloaded</i> Turcite Nut (S007)	100 (45)	800 (363)	60	15 (0,11)	(75)	< 0.008 (203)	(5)	+ 0.0002 to - 0.0082 (5) (208)		
	Preloaded Turcite Nut (S008)	90 (41)	800 (363)		30 (0,21)		0		+ 0.0002 to - 0.0002 (5) (5)		
dia. ead	Non-preloaded (S009)	590 (267)	2,425 (1100)	90	25 (0,18)		< 0.008 (203)		+ 0.0002 to - 0.0082 (5) (208)		
0.625 inch dia. 1.000 inch lead	Preloaded (S010)	530 (240)	2,390 (1084)		40 (0,28)	< 0.004	0	+/- 0.0002	+ 0.0002 <i>to</i> - 0.0002 (5) (5)		
0.6 1.0	<i>Non-preloaded</i> Turcite Nut (S011)	100 (45)	800 (363)	60	35 (0,25)	(100)	< 0.008 (203)	(5)	+ 0.0002 to - 0.0082 (5) (208)		
	Preloaded Turcite Nut (S012)	90 (41)	800 (363)		60 (0,42)		0		+ 0.0002 to - 0.0002 (5) (5)		

Footnotes:

(1) Dynamic load capacity of screw based on 1 million inches of travel (25Km).

(2) There is a 2.2 inch (55,9 mm) reduction of carriage travel (from the listed travel length) when using a preloaded nut with this screw option.



				WS					
	SCREW	Dyn. ⁽¹⁾ Capacity	Static Capacity	Screw Efficiency	Breakaway Torque	Position Accuracy	Backlash	Unidirectional Repeatability	Bidirectional Repeatability
		lbs (kg)	lbs (kg)	%	oz-in (N-m)	inch/ft (microns/300 mm)	inches (microns)	inches (microns)	inches (microns)
0.625 inch dia. 0.200 inch lead	Non-preloaded (S114)	876 (397)	2,700 (1224)	90	10 (0,07)	< 0.002	< 0.003 (76)	+/- 0.0002	+ 0.0002 <i>to</i> - 0.0032 (5) (81)
0.625 ir 0.200 in	Preloaded (S115)	788 (357)	2,430 (1102)		20 (0,14) (50)	0	(5)	+ 0.0002 <i>to</i> - 0.0002 (5) (5)	
16 mm dia. 5 mm lead	Non-preloaded (S116)	876 (397)	2,700 (1224)	90	10 (0,07)	< 0.002	< 0.003 (76)	+/- 0.0002 (5)	+ 0.0002 <i>to</i> - 0.0032 (5) (81)
16 mr 5 mm	Preloaded (S117)	788 (357)	2,430 (1102)		20 (0,14)	(50)	0		+ 0.0002 <i>to</i> - 0.0002 (5) (5)
mm dia. mm lead	Non-preloaded (S118)	1,080 (489)	2,630 (1192)	90	15 (0,11)	< 0.002	< 0.003 (76)	+/- 0.0002 (5)	+ 0.0002 <i>to</i> - 0.0032 (5) (81)
16 mr 10 mr	⁽²⁾ Preloaded (S119)	972 (440)	2,365 (1072)		25 (0,18)	(50)	0		+ 0.0002 <i>to</i> - 0.0002 (5) (5)
n dia. n lead	Non-preloaded (S120)	819 (371)	1,620 (734)	90	20 (0,14)	< 0.002	< 0.003 (76)	+/- 0.0002 (5)	+ 0.0002 <i>to</i> - 0.0032 (5) (81)
16 mm 16 mm	⁽³⁾ Preloaded (S121)	737 (334)	1,455 (659)	30	35 (0,24)	(50)	0		+ 0.0002 <i>to</i> - 0.0002 (5) (5)

Footnotes:

(1) Dynamic load capacity of screw based on 1 million inches of travel (25Km).

(2) There is a 0.5 inch (12,7 mm) reduction of carriage travel (from the listed travel length) when using a preloaded nut with this screw option.

(3) There is a 0.7 inch (17,8 mm) reduction of carriage travel (from the listed travel length) when using a preloaded nut with this screw option.

					GROUND BA	LL SCREV	/S ⁽²⁾			
SCREW	Dyn. ⁽¹⁾ Capacity	Static Capacity	Screw Efficiency	Breakaway Torque	Position Accuracy	Backlash inches (microns)	Unidirectional Repeatability	Bidirectional Repeatability inches (microns)		
	lbs (kg)	lbs (kg)	%	oz-in (N-m)	inch/ft (microns/300 mm)		inches (microns)			
0.625 dia., 0.200 lead Preloaded (S212)	987 (447)	3,080 (1397)	90	20 (0,14)	< 0.0012 (30)	0	+/- 0.0001 (2,5)	+ 0.0001 <i>to</i> - 0.0001 (2,5) (2,5)		
0.625 dia., 0.500 lead Preloaded (S213)	1430 (649)	4,191 (1901)	90	30 (0,21)	< 0.0012 (30)	0	+/- 0.0001 (2,5)	+ 0.0001 <i>to</i> - 0.0001 (2,5) (2,5)		
l6 mm dia., 5 mm lead Preloaded (S214)	987 (447)	3,080 (1397)	90	20 (0,14)	< 0.0012 (30)	0	+/- 0.0001 (2,5)	+ 0.0001 <i>to</i> - 0.0001 (2,5) (2,5)		
6 mm dia., 16 mm lead <i>Preloaded</i> (S215)	910 (412)	1,800 (816)	90	35 (0,24)	< 0.0012 (30)	0	+/- 0.0001 (2,5)	+ 0.0001 <i>to</i> - 0.000 ⁻ (2,5) (2,5)		

Footnotes:

(1) Dynamic load capacity of screw based on 1 million inches of travel (25Km).

(2) The Ground Ball Screw options are only available in travel lengths up to 36 inches (910 mm) of travel.



						ROLLED AC	ME SCREW	/S	
	SCREW		Static Capacity	Screw Efficiency	Breakaway Torque	Position Accuracy	Backlash	Unidirectional Repeatability	Bidirectional Repeatability
		lbs (kg)	lbs (kg)	%	oz-in (N-m)	inch/ft (microns/300 mm)	inches (microns)	inches (microns)	inches (microns)
inch dia. inch lead	<i>Non-preloaded</i> (S300)	160 (73)	800 (363)	40	10 (0,07)	< 0.003	< 0.008 (203)	+/- 0.0002	+ 0.0002 <i>to</i> - 0.0082 (5) (208)
0.625 i 0.100 ii	Preloaded (S301)	140 (64)	720 (327)		0	(5)	+ 0.0002 <i>to</i> - 0.0002 (5) (5)		
inch dia. inch lead	Non-preloaded (S302)	160 (73)	800 (363)	40	15 (0,11)	< 0.003	< 0.008 (203)	+/- 0.0002 (5)	+ 0.0002 <i>to</i> - 0.0082 (5) (208)
0.625 ir 0.200 ir	Preloaded (S303)	140 (64)	720 (327)		30 (0,21)	(75)	0		+ 0.0002 <i>to</i> - 0.0002 (5) (5)
m dia. רופס ה	Non-preloaded (S304)	160 (73)	800 (363)	40	15 (0,11)	< 0.003	< 0.008 (203)	+/- 0.0002	+ 0.0002 <i>to</i> - 0.0082 (5) (208)
16 mm 4 mm l	Preloaded (S305)	140 (64)	720 (327)		30 (0,21)	(75)	0	(5)	+ 0.0002 <i>to</i> - 0.0002 (5) (5)

Footnotes:

(1) Dynamic load capacity of screw based on 1 million inches of travel (25Km).

Single or Multiple Axis

Introduction

LINTECH's 140 series positioning tables offer precision performance and design flexibility for use in a wide variety of Motion Control applications.

- Welding
- Test Stands
- Part Insertion
- Laser Positioning
- Liquid Dispensing
- Inspection Stations

Gluing

General Automation

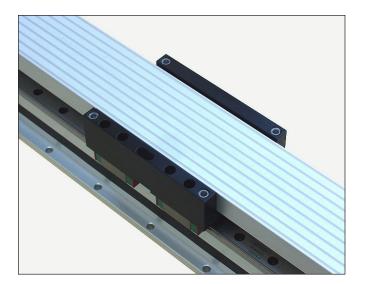
Pick & Place

Part Scanning

Semiconductor Processing

Quality Construction

LINTECH's 140 series tables are designed to handle light loads at very high speeds. These tables use a low friction, preloaded, recirculating linear ball bearing system, which rides on precision ground linear rails. The linear rails are mounted to a precision machined aluminum base, which offers a rigid support over the entire travel of the table's carriage. The load is mounted to a precision machined aluminum carriage, which has threaded stainless steel inserts for high strength and wear life. The drive system uses two pulleys, along with a high strength, steel reinforced polyure-thane belt, which provides 3.543 inches (90 mm) of linear movement per revolution of the input shaft. The simple belt tensioning system allows for easy adjustment of belt tension by the user. NEMA 23 & 34 motor mounts, or gearhead mounts are available as well as planetary gearheads.



Available Options

Carriage Adapter Plates & Vertical Angle Brackets

Optional carriage adapter plates and vertical angle brackets can be mounted directly to the top of various *LINTECH* positioning tables, thus providing for easy multiple axis configurations.

End of Travel and Home Switches

The 140 series tables can be provided with end of travel (EOT) and home switches mounted and wired for each axis. Most position controllers can utilize the EOT switches to stop carriage motion when the extreme table travel has been reached in either direction. The home switch provides a known mechanical location on the table.

Motor Adapter Brackets

NEMA 34 or any metric mount motor can be mounted to a 140 series positioning table with the use of adapter brackets.

Rotary Encoders

Incremental rotary encoders can be mounted to the table in order to provide positional data back to either a motion controller, or a digital display.

Other

The 140 series tables can accommodate **chrome plated linear bearings & rails** for corrosive environment applications and **power-off electric brakes** for load locking applications.



Standard Features - 140 Series

- Compact 2.875 inches (73 mm) wide by 3.000 inches (76 mm) tall
- Travel lengths from 4 inches (100 mm) to 10 feet (3,0 meters)
- Threaded stainless steel inserts in carriage for load mounting
- Polyurethane belt with high strength steel tension members
- $\hfill\square$ 0° F to +176° F (-18° C to +80° C) operating temperature
- Single screw belt tensioning with self locking thread
- Dynamic Load Capacity to 200 lbs (90 kg)
- Recirculating linear ball bearing system
- Precision ground square rail design
- 1 rail, 1 or 2 bearing carriages

140-CP0 Series

140-CP1 Series



140-CP2 Series



Options - 140 Series

- AUTOCAD[®] drawings available via the internet
- $\hfill\square$ End of travel (EOT) and home switches wired
- Adapter brackets for non-NEMA motors
- Chrome plated linear bearings & rails
- Rotary incremental encoders
- NEMA 34 adapter bracket
- Power-off electric brakes
- Carriage adapter plates
- Vertical angle bracket
- Motor couplings

Ordering Guide

Table Series							
lumber of Bearing	gs						
1 - 1 bearing per c	arriage						
2 - 2 bearings per	carriage						
Carriage Length _							
4 - 4 inches		-					
-	pages B-24, B-26 & B-28)						
004 - 4 to 120 inch	nes						
Cover Plate							
CP0 - no cover	·	CP2 - top					
plate	plate only	COVE	er plates				
Carriage Inserts (a	ee pages B-25, B-27 & B-29) _						
1 - English mount	2 - Metric mount			-			
	es B-25, B-27 & B-29)						
Distant in the set of							
	ngle shaft D3 - Right						
	ngle shaft D3 - Right gle shaft D4 - Left H						
D2 - Left Hand sing		land thru sha	aft				
D2 - Left Hand sing	gle shaft D4 - Left H ages B-25, B-27, B-29 & B-42)	land thru sha	aft	NEMA 34 moun	t (E)		
D2 - Left Hand sing	gle shaft D4 - Left H ages B-25, B-27, B-29 & B-42) M02 - NEM	land thru sha	aft (E) M04 -	NEMA 34 moun NEMA 34 moun	. ,		
D2 - Left Hand sing Notor Mount (see pr M00 - none M99 - other	gle shaft D4 - Left H ages B-25, B-27, B-29 & B-42) M02 - NEM M03 - NEM	land thru sha IA 23 mount IA 23 mount	aft (E) M04 -		. ,		
D2 - Left Hand sing Motor Mount (see pr M00 - none M99 - other	gle shaft D4 - Left H ages B-25, B-27, B-29 & B-42) M02 - NEM	land thru sha IA 23 mount IA 23 mount	aft (E) M04 -		. ,		
D2 - Left Hand sing Notor Mount (see pr M00 - none M99 - other Coupling Options (s	gle shaft D4 - Left H ages B-25, B-27, B-29 & B-42) M02 - NEM M03 - NEM see pages B-38 & B-39)	Iand thru sha IA 23 mount IA 23 mount IA 23 mount C407 to C	(E) <u>M04 -</u> (M) <u>M05 -</u>		. ,		
D2 - Left Hand sing Notor Mount (see pr M00 - none M99 - other Coupling Options (s C000 - none	gle shaft D4 - Left H ages B-25, B-27, B-29 & B-42) M02 - NEM M03 - NEM see pages B-38 & B-39) C130 to C134 - H100	Iand thru sha IA 23 mount IA 23 mount IA 23 mount C407 to C C435 to C	(E) M04 - (M) M05 - C413 - G100		. ,		
D2 - Left Hand sing Motor Mount (see pr M00 - none M99 - other Coupling Options (s C000 - none C999 - none	gle shaft D4 - Left H ages B-25, B-27, B-29 & B-42) M02 - NEM M03 - NEM see pages B-38 & B-39) C130 to C134 - H100 C155 to C164 - H131 C190 to C200 - H163	land thru sha IA 23 mount IA 23 mount IA 23 mount C407 to C C435 to C C470 to C	(E) M04 - (M) M05 - C413 - G100 C444 - G126		. ,		
D2 - Left Hand sing Notor Mount (see pr M00 - none M99 - other Coupling Options (s C000 - none C999 - none	gle shaft D4 - Left H ages B-25, B-27, B-29 & B-42) M02 - NEM M03 - NEM see pages B-38 & B-39) C130 to C134 - H100 C155 to C164 - H131	land thru sha IA 23 mount IA 23 mount IA 23 mount C407 to C C435 to C C470 to C	(E) M04 - (M) M05 - C413 - G100 C444 - G126		. ,		
D2 - Left Hand sing Motor Mount (see pr M00 - none M99 - other Coupling Options (s C000 - none C999 - none	gle shaft D4 - Left H ages B-25, B-27, B-29 & B-42) M02 - NEM M03 - NEM see pages B-38 & B-39) C130 to C134 - H100 C155 to C164 - H131 C190 to C200 - H163	Iand thru sha IA 23 mount IA 23 mount IA 23 mount C407 to C C435 to C	(E) M04 - (M) M05 - 2413 - G100 2444 - G126 2480 - G158	NEMA 34 moun	t (M)		
D2 - Left Hand sing Motor Mount (see pr M00 - none M99 - other Coupling Options (s C000 - none C999 - none Limit & Home Switt L00 - no switches	gle shaft D4 - Left H ages B-25, B-27, B-29 & B-42) M02 - NEM M03 - NEM see pages B-38 & B-39) C130 to C134 - H100 C155 to C164 - H131 C190 to C200 - H163 tches (see pages B-35 to B-37) EOT & home switches EOT switches only	Iand thru sha IA 23 mount IA 23 mount IA 23 mount C407 to C C435 to C C470 to C Reed L04 L05	(E) M04 - (M) M05 - 2413 - G100 2444 - G126 2480 - G158 Hall L07 L08	NEMA 34 moun Prox (NPN) L10 L11	Prox (PNP) L13 L14		
D2 - Left Hand sing Motor Mount (see pr M00 - none M99 - other Coupling Options (s C000 - none C999 - none Limit & Home Switt L00 - no switches	gle shaft D4 - Left H ages B-25, B-27, B-29 & B-42) M02 - NEM M03 - NEM see pages B-38 & B-39) C130 to C134 - H100 C155 to C164 - H131 C190 to C200 - H163 Aches (see pages B-35 to B-37) EOT & home switches	Iand thru sha IA 23 mount IA 23 mount IA 23 mount C407 to C C435 to C C470 to C Reed L04	(E) M04 - (M) M05 - 2413 - G100 2444 - G126 2480 - G158 Hall L07	NEMA 34 moun Prox (NPN) L10	Prox (PNP) L13		
D2 - Left Hand sing Notor Mount (see pr M00 - none M99 - other Coupling Options (s C000 - none C999 - none .imit & Home Switt L00 - no switches L99 - other	gle shaft D4 - Left H ages B-25, B-27, B-29 & B-42) M02 - NEM M03 - NEM see pages B-38 & B-39) C130 to C134 - H100 C155 to C164 - H131 C190 to C200 - H163 tches (see pages B-35 to B-37) EOT & home switches EOT switches only home switch only	Iand thru sha IA 23 mount IA 23 mount IA 23 mount C407 to C C435 to C C470 to C Reed L04 L05	(E) M04 - (M) M05 - 2413 - G100 2444 - G126 2480 - G158 Hall L07 L08	NEMA 34 moun Prox (NPN) L10 L11	Prox (PNP) L13 L14		
D2 - Left Hand sing Motor Mount (see pr M00 - none M99 - other Coupling Options (s C000 - none C999 - none Limit & Home Swit L00 - no switches L99 - other	gle shaft D4 - Left H ages B-25, B-27, B-29 & B-42) M02 - NEM M03 - NEM see pages B-38 & B-39) C130 to C134 - H100 C155 to C164 - H131 C190 to C200 - H163 tches (see pages B-35 to B-37) EOT & home switches EOT switches only home switch only	Iand thru sha IA 23 mount IA 23 mount IA 23 mount C407 to C C435 to C C470 to C Reed L04 L05 L06	(E) M04 - (M) M05 - 2413 - G100 2444 - G126 2480 - G158 Hall L07 L08 L09	NEMA 34 moun Prox (NPN) L10 L11	Prox (PNP) L13 L14		
D2 - Left Hand sing Motor Mount (see pr M00 - none M99 - other Coupling Options (s C000 - none C999 - none Limit & Home Switt L00 - no switches L99 - other Encoder Options (s E00 - none E01 - rotary (500 li	gle shaft D4 - Left H ages B-25, B-27, B-29 & B-42) M02 - NEM M03 - NEM See pages B-38 & B-39) C130 to C134 - H100 C155 to C164 - H131 C190 to C200 - H163 tches (see pages B-35 to B-37) EOT & home switches EOT switches only home switch only see page B-45) E02 - rotary (1	Iand thru sha IA 23 mount IA 23 mount IA 23 mount C407 to C C435 to C C470 to C Reed L04 L05 L06	(E) M04 - (M) M05 - (413 - G100 (444 - G126 (480 - G158 Hall L07 L08 L09 () E99 - () E99 -	NEMA 34 moun Prox (NPN) L10 L11 L12	Prox (PNP) L13 L14		

note: When selecting any brake option, the Drive Shaft D3 or D4 above is required.

(E) - English Interface (M) - Metric Interface



- Belt Drive -

Specifications

Load Ca	pacities	One	(1) Bea	aring	g Car	riage	Two) (2) Bea	aring	g Carı	riage
Dynamic Horizontal	2 million inches (50 km) of travel	100	lbs	(45	kg)	200	lbs	(90	kg)
Dynamic Horizontal	50 million inches (1270 km) of travel	34	lbs	(15	kg)	68	lbs	(30	kg)
Static Horizontal		200	lbs	(90	kg)	400	lbs	(180	kg)
Dynamic Roll Moment	2 million inches (50 km) of travel	8	ft-lbs	(11	N-m)	16	ft-lbs	(22	N-m)
Dynamic Roll Moment	50 million inches (1270 km) of travel	3	ft-lbs	(4	N-m)	5	ft-lbs	(7	N-m)
Static Roll Moment		14	ft-lbs	(19	N-m)	28	ft-lbs	(38	N-m)
Dyn. Pitch & Yaw Moment	2 million inches (50 km) of travel	4	ft-lbs	(5,4	N-m)	15	ft-lbs	(20	N-m)
Dyn. Pitch & Yaw Moment	50 million inches (1270 km) of travel	1	ft-lbs	(1,9) N-m)	5	ft-lbs	(7	N-m)
Static Pitch & Yaw Moment		8	ft-lbs	(10	N-m)	30	ft-lbs	(40	N-m)
Each Bearing Dyn. Capacity	2 million inches (50 km) of travel	100	lbs	(45	kg)	100	lbs	(45	kg)
Each Bearing Dyn. Capacity	50 million inches (1270 km) of travel	34	lbs	(15	kg)	34	lbs	(15	kg)
Each Bearing Static Load C	apacity	200	lbs	(90	kg)	200	lbs	(90	kg)
Maximum Belt Tensile Force)	250	lbs	(113	kg)	250	lbs	(113	kg)
Maximum Carriage Thrust F	orce	115	lbs	(52	kg)	115	lbs	(52	kg)
Maximum Speed		78	in/sec	(2	m/sec)	78	in/sec	(2 n	n/sec)
Maximum Acceleration		193	in/sec ²	(4,9	m/sec²)	386	in/sec ²	(9,8 n	n/sec²)
d ₂ Center to center distance (spacin	g) of each bearing on a single rail			-			2	.088 in	(5	53,0	mm)
$\mathbf{d}_{\mathbf{r}}$ Center distance of the bearing to	top of carriage plate surface	1.	375 in	(:	34,9	mm)	1	.375 in	(3	34,9	mm)

Other	For One (1) & Two (2) Bearing Carriages					
Table Material	Base, Carriage, End Plates, & Cover Plate - 6061 anodized aluminum					
Linear Rail Material	Stainless Steel					
Belt Properties	Black, 16 mm wide, Polyurethane, Steel reinforced belt					
Drive Pulley Weight	0.21 lbs (0,10 kg)					
Drive Pulley Diameter	1.128 in (28,65 mm)					
Drive Lead	3.543 in (90,00 mm)					
Belt Stretch - x Load (lbs or N)	0.00025 in/ft per lbs (0,00476 mm/m per N)					
Unidirectional Repeatability	+/- 0.001 in (+/- 0,0254 mm)					
Bidirectional Repeatability	+/- 0.004 in (+/- 0,1016 mm)					
Position Accuracy (Belt) (1)	< 0.010 in/ft (< 0,254 mm/300mm)					
Orthogonality (multi-axis systems)	< 30 arc-seconds					
Friction Coefficient	< 0.01					
Breakaway Torque	< 40 oz-in (0,282 N-m)					
Motor Mount	NEMA 23 & 34 Mounts, Metric Mounts, and Gearheads					
Coupling	Two (2) different styles available					

Footnotes:

(1) Position accuracy varies based on belt stretch. The given rating is based upon a carriage speed of 5 inches/sec (127 mm/sec) and a no load condition.

Dimensions & Specifications

- Without Cover Plates -

Model Number	Travel Length inches	inc	m ensions hes ^{m)}		Dimen ches (mm)	sions	Belt Weight ounces	Table ⁽¹⁾ Weight Ibs
	(mm)	А	В	С	E	М	(gm)	(kg)
14x4004-CP0	4 (100)	8.0 (203,2)	14.0 (355,6)	1.188 (30,2)	3	8	1.3 (36,8)	4.8 (2,2)
14x4006-CP0	6 (150)	10.0 (254,0)	16.0 (406,4)	0.313 (8,0)	5	12	1.5 (42,5)	5.3 (2,4)
14x4008-CP0	8 (200)	12.0 (304,8)	18.0 (457,2)	1.313 (33,4)	5	12	1.7 (48,2)	5.8 (2,6)
14x4012-CP0	12 (300)	16.0 (406,4)	22.0 (558,8)	1.438 (36,5)	7	16	2.1 (59,5)	6.3 (2,9)
14x4016-CP0	16 (405)	20.0 (508,0)	26.0 (660,4)	1.563 (39,7)	9	20	2.5 (70,9)	7.3 (3,3)
14x4020-CP0	20 (505)	24.0 (609,6)	30.0 (762,0)	1.688 (42,9)	11	24	2.9 (82,2)	8.3 (3,8)
14x4024-CP0	24 (605)	28.0 (711.2)	34.0 (863,6)	1.813 (46,1)	13	28	3.3 (93,6)	9.3 (4,2)
14x4030-CP0	30 (760)	34.0 (863,6)	40.0 (1016,0)	1.063 (27,0)	17	36	3.9 (110,6)	10.3 (4,7)
14x4036-CP0	36 (910)	40.0 (1016,0)	46.0 (1168,4)	0.313 (8,0)	21	44	4.5 (127,6)	11.8 (5,4)
14x4042-CP0	42 (1060)	46.0 (1168,4)	52.0 (1320,8)	1.438 (36,5)	23	48	5.1 (144,6)	13.3 (6,0)
14x4048-CP0	48 (1215)	52.0 (1320,8)	58.0 (1473,2)	0.688 (17,5)	27	56	5.7 (161,6)	14.8 (6,7)
14x4054-CP0	54 (1370)	58.0 (1473,2)	64.0 (1625,6)	1.813 (46,1)	29	60	6.3 (178,6)	16.3 (7,4)
14x4060-CP0	60 (1520)	64.0 (1625,6)	70.0 (1778,0)	1.063 (27,0)	33	68	6.9 (195,6)	17.8 (8,1)
14x4072-CP0	72 (1820)	76.0 (1930,4)	82.0 (2082,8)	0.500 (12,7)	39	80	8.1 (229,6)	20.8 (9,4)
14x4084-CP0	84 (2130)	88.0 (2235,2)	94.0 (2387,6)	0.875 (22,2)	45	92	9.3 (263,7)	23.8 (10,8)
14x4096-CP0	96 (2435)	100.0 (2540,0)	106.0 (2692,4)	0.313 (8,0)	51	104	10.5 (297,7)	26.8 (12,2)
14x4108-CP0	108 (2740)	112.0 (2844,8)	118.0 (2997,2)	0.688 (17,5)	57	116	11.7 (331,7)	29.8 (13,5)
14x4120-CP0	120 (3045)	124.0 (3149,6)	130.0 (3302,0)	1.063 (27,0)	63	128	12.9 (365,7)	32.8 (14,9)

x = 1; Carriage has 1 bearing; Carriage weight = 1.4 lbs. (0,64 kg)

x = 2; Carriage has 2 bearings; Carriage weight = 1.5 lbs. (0,68 kg)

Footnotes:

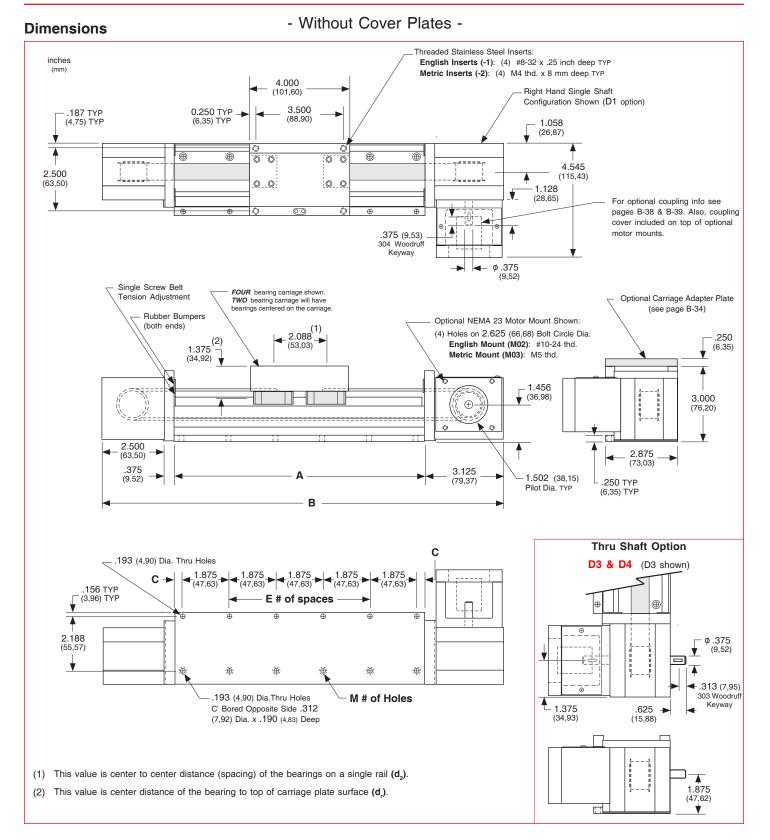
(1) Weight shown is with a 1 bearing carriage [1.4 lbs (0,64 kg)], a NEMA 23 motor mount [0.34 lbs (0,16 kg)], and a H100 style [0.08 lbs (0,04 kg)] coupling. When using a 2 bearing carriage add 0.1 lbs (0,04 kg) to each value.



Technical Reference

- Belt Drive -

140-CP0 Series



Note: Any 130 or 140 series table can be mounted on top of a second 130 or 140 series table, in order to create X-Y multiple axis configurations. *LINTECH* recommends that a 2 bearing carriage be used for the bottom axis, and that the top axis should never extend out more than 18 inches in either direction, from the bottom axis carriage edge, without the use of a support bearing system on the outer edges of the top axis. The 130-CP1, 130-CP2 or 140 series requires a **Carriage Adapter Plate** option. The carriage's threaded stainless steel insert hole pattern exactly matches the base mounting hole pattern on each table, therefore no adapter bracket or extra machining is required. However a precision square tool, or micrometer depth gauge, is required in order to obtain an orthogonality between the two tables of < 30 arc-seconds. The table base, carriage top & carriage sides are all precision machined. *LINTECH*'s 100 or 120 series tables should be used for the bottom axis in a multiple axes application for better system rigidity, performance, and life.

Dimensions & Specifications

- With Top Cover Plate Only -

Model Trave Number inche		inc	mensions hes m)		Dimens ches mm)	sions	Belt Weight ounces	Table ⁽¹⁾ Weight Ibs
	(mm)	А	В	С	E	М	(gm)	(kg)
14x4004-CP1	4 (100)	8.0 (203,2)	14.0 (355,6)	1.188 (30,2)	3	8	1.3 (36,8)	4.8 (2,2)
14x4006-CP1	6 (150)	10.0 (254,0)	16.0 (406,4)	0.313 (8,0)	5	12	1.5 (42,5)	5.3 (2,4)
14x4008-CP1	8 (200)	12.0 (304,8)	18.0 (457,2)	1.313 (33,4)	5	12	1.7 (48,2)	5.8 (2,6)
14x4012-CP1	12 (300)	16.0 (406,4)	22.0 (558,8)	1.438 (36,5)	7	16	2.1 (59,5)	6.3 (2,9)
14x4016-CP1	16 (405)	20.0 (508,0)	26.0 (660,4)	1.563 (39,7)	9	20	2.5 (70,9)	7.3 (3,3)
14x4020-CP1	20 (505)	24.0 (609,6)	30.0 (762,0)	1.688 (42,9)	11	24	2.9 (82,2)	8.3 (3,8)
14x4024-CP1	24 (605)	28.0 (711.2)	34.0 (863,6)	1.813 (46,1)	13	28	3.3 (93,6)	9.3 (4,2)
14x4030-CP1	30 (760)	34.0 (863,6)	40.0 (1016,0)	1.063 (27,0)	17	36	3.9 (110,6)	10.3 (4,7)
14x4036-CP1	36 (910)	40.0 (1016,0)	46.0 (1168,4)	0.313 (8,0)	21	44	4.5 (127,6)	11.8 (5,4)
14x4042-CP1	42 (1060)	46.0 (1168,4)	52.0 (1320,8)	1.438 (36,5)	23	48	5.1 (144,6)	13.3 (6,0)
14x4048-CP1	48 (1215)	52.0 (1320,8)	58.0 (1473,2)	0.688 (17,5)	27	56	5.7 (161,6)	14.8 (6,7)
14x4054-CP1	54 (1370)	58.0 (1473,2)	64.0 (1625,6)	1.813 (46,1)	29	60	6.3 (178,6)	16.3 (7,4)
14x4060-CP1	60 (1520)	64.0 (1625,6)	70.0 (1778,0)	1.063 (27,0)	33	68	6.9 (195,6)	17.8 (8,1)

x = 1; Carriage has 1 bearing; Carriage weight = 1.4 lbs. (0,64 kg)

x = 2; Carriage has 2 bearings; Carriage weight = 1.5 lbs. (0,68 kg)

Footnotes:

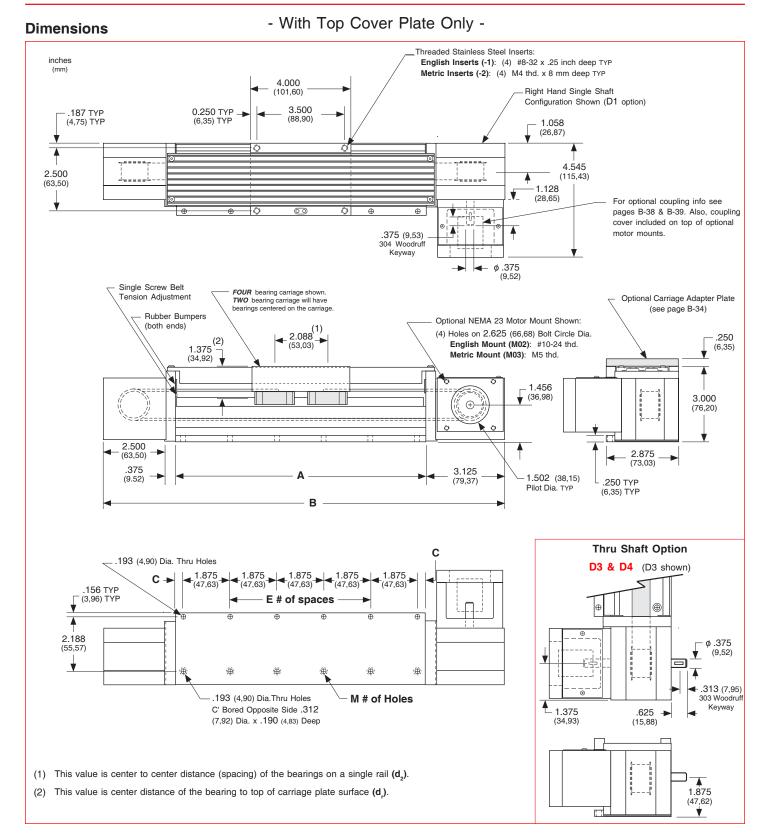
(1) Weight shown is with a 1 bearing carriage [1.4 lbs (0,64 kg)], a NEMA 23 motor mount [0.34 lbs (0,16 kg)], and a H100 style [0.08 lbs (0,04 kg)] coupling. When using a 2 bearing carriage add 0.1 lbs (0,04 kg) to each value.



Technical Reference

- Belt Drive -

140-CP1 Series



Note: Any 130 or 140 series table can be mounted on top of a second 130 or 140 series table, in order to create X-Y multiple axis configurations. *LINTECH* recommends that a 2 bearing carriage be used for the bottom axis, and that the top axis should never extend out more than 18 inches in either direction, from the bottom axis carriage edge, without the use of a support bearing system on the outer edges of the top axis. The 130-CP1, 130-CP2 or 140 series requires a **Carriage Adapter Plate** option. The carriage's threaded stainless steel insert hole pattern exactly matches the base mounting hole pattern on each table, therefore no adapter bracket or extra machining is required. However a precision square tool, or micrometer depth gauge, is required in order to obtain an orthogonality between the two tables of < 30 arc-seconds. The table base, carriage top & carriage sides are all precision machined. *LINTECH*'s 100 or 120 series tables should be used for the bottom axis in a multiple axes application for better system rigidity, performance, and life.

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Dimensions & Specifications

- With Top Cover Plate Only -

Model Number	Travel Length inches	inc	mensions hes m)		Dimens iches mm)	sions	Belt Weight ounces	Table ⁽¹⁾ Weight Ibs
	(mm)	А	В	С	E	М	(gm)	(kg)
14x4004-CP2	4 (100)	8.0 (203,2)	14.0 (355,6)	1.188 (30,2)	3	8	1.3 (36,8)	5.0 (2,3)
14x4006-CP2	6 (150)	10.0 (254,0)	16.0 (406,4)	0.313 (8,0)	5	12	1.5 (42,5)	5.5 (2,5)
14x4008-CP2	8 (200)	12.0 (304,8)	18.0 (457,2)	1.313 (33,4)	5	12	1.7 (48,2)	6.0 (2,7)
14x4012-CP2	12 (300)	16.0 (406,4)	22.0 (558,8)	1.438 (36,5)	7	16	2.1 (59,5)	6.6 (3,0)
14x4016-CP2	16 (405)	20.0 (508,0)	26.0 (660,4)	1.563 (39,7)	9	20	2.5 (70,9)	7.7 (3,5)
14x4020-CP2	20 (505)	24.0 (609,6)	30.0 (762,0)	1.688 (42,9)	11	24	2.9 (82,2)	8.7 (3,9)
14x4024-CP2	24 (605)	28.0 (711.2)	34.0 (863,6)	1.813 (46,1)	13	28	3.3 (93,6)	9.8 (4,5)
14x4030-CP2	30 (760)	34.0 (863,6)	40.0 (1016,0)	1.063 (27,0)	17	36	3.9 (110,6)	10.9 (5,0)
14x4036-CP2	36 (910)	40.0 (1016,0)	46.0 (1168,4)	0.313 (8,0)	21	44	4.5 (127,6)	12.5 (5,7)
14x4042-CP2	42 (1060)	46.0 (1168,4)	52.0 (1320,8)	1.438 (36,5)	23	48	5. 1 (144,6)	14.0 (6,4)
14x4048-CP2	48 (1215)	52.0 (1320,8)	58.0 (1473,2)	0.688 (17,5)	27	56	5.7 (161,6)	15.6 (7,1)
14x4054-CP2	54 (1370)	58.0 (1473,2)	64.0 (1625,6)	1.813 (46,1)	29	60	6.3 (178,6)	17.2 (7,8)
14x4060-CP2	60 (1520)	64.0 (1625,6)	70.0 (1778,0)	1.063 (27,0)	33	68	6.9 (195,6)	18.8 (8,5)

x = 1; Carriage has 1 bearing; Carriage weight = 1.4 lbs. (0,64 kg)

- x = 2; Carriage has 2 bearings; Carriage weight = 1.5 lbs. (0,68 kg)

Footnotes:

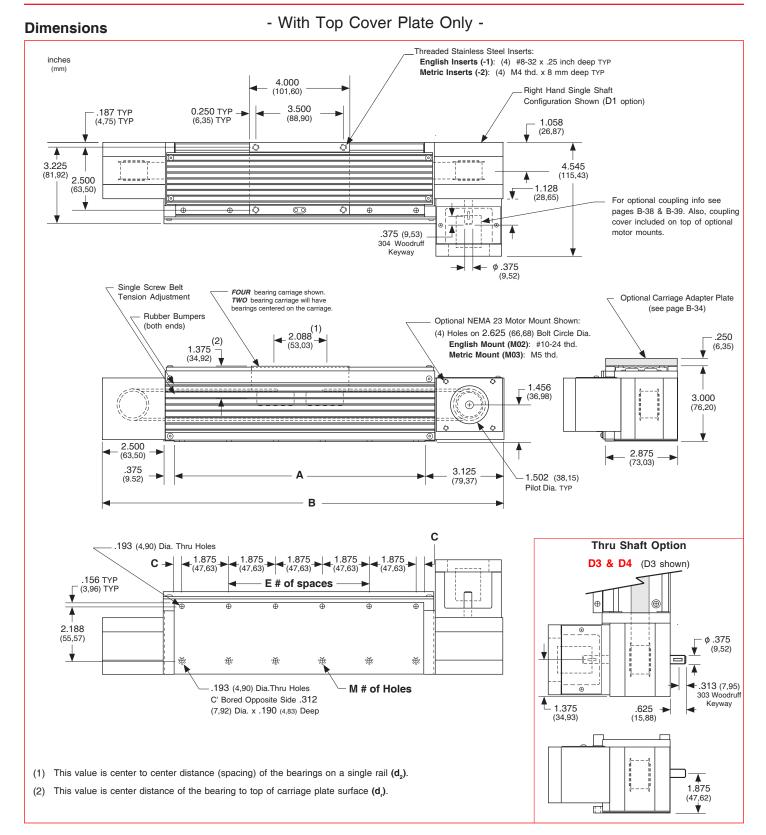
(1) Weight shown is with a 1 bearing carriage [1.4 lbs (0,64 kg)], a NEMA 23 motor mount [0.34 lbs (0,16 kg)], and a H100 style [0.08 lbs (0,04 kg)] coupling. When using a 2 bearing carriage add 0.1 lbs (0,04 kg) to each value.



Technical Reference

- Belt Drive -

140-CP2 Series



Note: Any 130 or 140 series table can be mounted on top of a second 130 or 140 series table, in order to create X-Y multiple axis configurations. *LINTECH* recommends that a 2 bearing carriage be used for the bottom axis, and that the top axis should never extend out more than 18 inches in either direction, from the bottom axis carriage edge, without the use of a support bearing system on the outer edges of the top axis. The 130-CP1, 130-CP2 or 140 series requires a **Carriage Adapter Plate** option. The carriage's threaded stainless steel insert hole pattern exactly matches the base mounting hole pattern on each table, therefore no adapter bracket or extra machining is required. However a precision square tool, or micrometer depth gauge, is required in order to obtain an orthogonality between the two tables of < 30 arc-seconds. The table base, carriage top & carriage sides are all precision machined. *LINTECH*'s 100 or 120 series tables should be used for the bottom axis in a multiple axes application for better system rigidity, performance, and life.

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- Belt Drive -

Maximum Motor Input Torque, Maximum Belt Force, & Maximum Acceleration Rate

Maximum Motor Input Torque

The maximum safe speed/torque of a motor/drive system that can be used with the 140 series, is limited by the belt strength at a given speed. The maximum linear forces the belt can adequately handle are determined by the number of teeth on the pulley and the belt width. The chart below illustrates the relationship between motor input torque/belt force and carriage speed. Care should be taken when sizing and selecting a motor/drive system for use with a 140 series table. Exceeding the maximum input torque values at the listed speeds can cause belt "skipping" over pulley teeth. This will result in mis-positioning of the carriage.

Maximum Acceleration

The maximum acceleration rate using a 140 series table can be determined by the simple equation $\mathbf{F} = \mathbf{M} \mathbf{x} \mathbf{A}$. Knowing the mass of the load, and the maximum safe operating force for the belt, the maximum possible acceleration rate can be determined. Note: The mechanical limitation for acceleration of the 140 series table is 1 g.

Maximum Acceleration Example

F	=	M × A
F	=	maximum belt force at desired speed
Μ	=	user applied load
Α	=	maximum acceleration rate (g's)

Sin Ø = angle of table from horizontal (degrees)

Horizontal Application

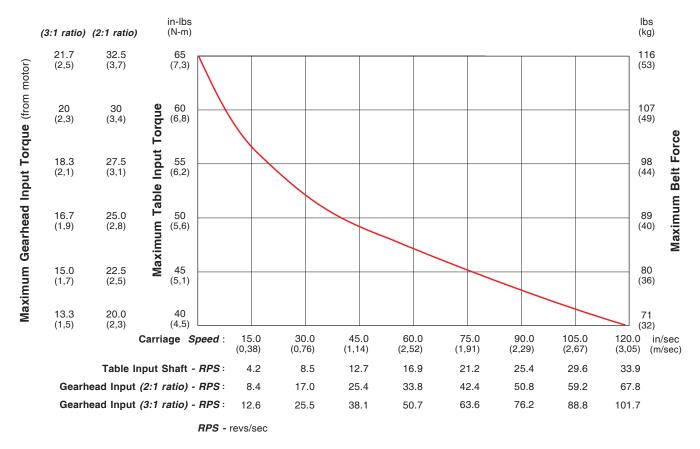
izontal Application	Vertical Application			
	F - M Sin φ			
A - <u>M</u>	A - <u>M</u>			

Example: A 30 lb load is mounted to a 140 series carriage in a horizontal application. Determine the maximum accel rate in g's & in/sec2 that can be used to achieve a maximum speed of 75 IPS.

- Step 1: From graph below, determine the maximum belt force at 75 IPS : (F = 80 lbs)
- Step 2: Add up your total mass = load weight + carriage weight : (M = 30 + 1.8 = 31.8 lbs)
- Step 3: Solve for A : (A = 80/31.8 = 2.5 g's)

Note: 1 g = 386 in/sec²

- Step 4: 2.5 g's x 386 = 968 in/sec²
- Step 5: Cannot exceed the 1.0 g mechanical limitation.



1) Table friction & breakaway forces have already been deducted from the above maximum belt force values.

2) Curve based upon maximum belt values. Select a motor coupling that can handle the required torque.



Master/Slave 140 Series Configuration

For some X-Y belt drive applications, the master/slave configuration shown to the right may be required. This system provides two bottom (X) axes spread apart a set distance, yet driven by one motor. The spreading of the two bottom axes minimizes the deflection on the Y axis, reduces the moment loading on the X axes carriages, increases the system rigidity, and prevents twisting of the Y axis as it accelerates to a set speed. LINTECH can provide the shaft supports, the cross shaft, the couplings, and the 140 series belt drive table without a motor mount bracket. The shaft supports are required as the couplings DO NOT provide adequate support of the shaft by themselves. Also, the shaft supports prevent the cross shaft from "whipping" at long lengths and high speeds.

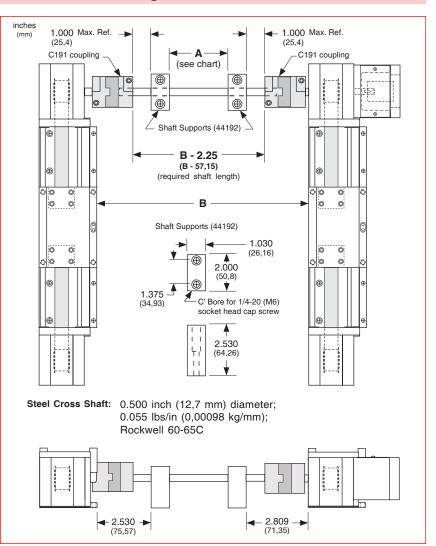
The chart below lists the maximum carriage speed available with a given distance between shaft supports. A minimum of two shaft supports is always required. More than two can be used to increase the speed of a longer spread system. The equations below show the relationship between the # of shaft supports, the spread between the two bottom axes (B), and the distance between individual shaft supports (A).

A = distance between shaft supports **B** = distance between 2 bottom axes

2 Shaft Supports:	A = [B - 7.50 in (190,5 mm)]
3 Shaft Supports:	A = [B - 8.53 in (216,7 mm)] / 2
4 Shaft Supports:	A = [B - 9.56 in (242,8 mm)] / 3

Maximum Distance Between Shaft Supports		Maximum Shaft Speed	Equivalent Carriage Speed		
	А				
(ir	nches)	(mm)	(RPM)	(in/sec)	(mm/sec)
<=	30	762	2000	118	3000
<=	36	914	1500	89	2250
<=	48	1219	840	50	1260
<=	54	1372	660	39	990
<=	60	1524	535	32	802
<=	66	1676	440	26	660
<=	72	1829	370	22	555
<=	84	2134	270	16	405
<=	96	2438	208	12	312
<= 1	08	2743	164	10	246
<= 1	20	3048	133	8	200

Note: The user is required to supply the mounting surface for the above configurations. LINTECH normally only supplies all the positioning hardware. A common base plate can be provided by LINTECH upon request.

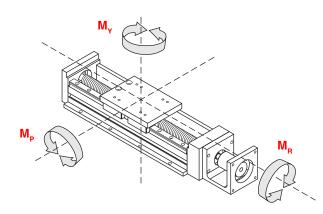


Linear Bearing Load Capacities

The following equation, and graphs, can be used to help determine the linear bearing life, and load capacity, of a 130 or 140 series positioning table.

$$L = \left[\frac{R}{F \times S}\right]^3 \times B$$

- L = calculated travel life (millions of inches or Km)
- **R** = rated dynamic load capacity of carriage (or each bearing) at 2 million inches of travel or 50 Km
- **F** = user applied load
- S = safety factor (1 to 8)
- **B** = either 2 (for millions of inches) or 50 (for Km)



Dynamic Moment Load (M_R) Capacity

Load applied away from Carriage Center

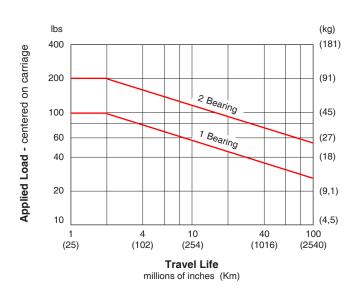
travel life		1 Bearing		2 Bearing	
millions of inches	(Km)	ft-lbs	(N-m)	ft-lbs	(N-m)
2	(50)	8.0	(10,8)	16	(22)
50	(1270)	2.7	(3,7)	5	(7)
100	(2540)	2.2	(3,0)	4	(5)
Ra	tings are bas	ed on d _a = 12	inches (305 mr	n) & d, = 0	

ft-lbs (N-m) 40 (54) Applied Load - from carriage center 20 (27) 2 Bearing 10 (14) 6 1 Bearing (8,1) 4 (5,4) 2 (2,7)1 (1,4)4 10 40 100 1 (25) (102) (254) (1016) (2540) Travel Life millions of inches (Km)

Specifications subject to change without notice

Dynamic Horizontal Load Capacity

-oud contorod on callago							
travel life		1 Bearing		2 Bearing			
millions of inches	(Km)	lbs	(kg)	lbs	(kg)		
2	(50)	100	(45)	200	(90)		
50	(1270)	34	(15)	68	(30)		
100	(2540)	27	(12)	54	(24)		



Dynamic Moment Load ($M_P \& M_\gamma$) Capacity

Load applied away from Carriage Center

travel life		1 Bearing		2 Bearing	
millions of inches	(Km)	ft-lbs	(N-m)	ft-lbs	(N-m)
2	(50)	4.0	(5,4)	15	(20)
50	(1270)	1.4	(1,9)	5	(7)
100	(2540)	1.1	(1,5)	4	(5)

Ratings are based on $d_3 = 0 \& d_4 = 12$ inches (305 mm)

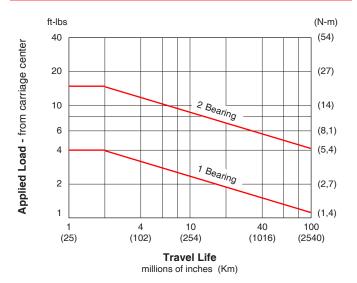
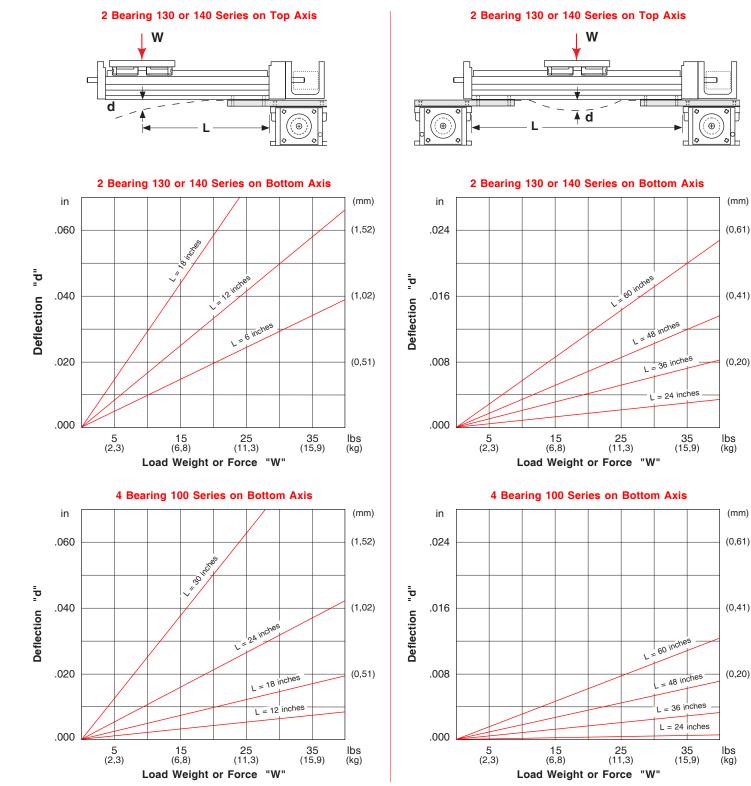


Table Deflection - Multiple Axis Configurations

The following graphs can be used to estimate the deflection value for a given configuration. The information in the graphs was obtained with the bottom axis firmly mounted to a granite surface plate and also includes the deflection of the bottom axis carriage assembly & all mounting hardware. Individual applications will vary depending on the user mounting surface, user mounting hardware, and user mounting configuration. If the deflection values below are too high for your application, a steel sub plate, or aluminum cross member, can be added for additional "Y" axis support. Contact *LINTECH* for more details.



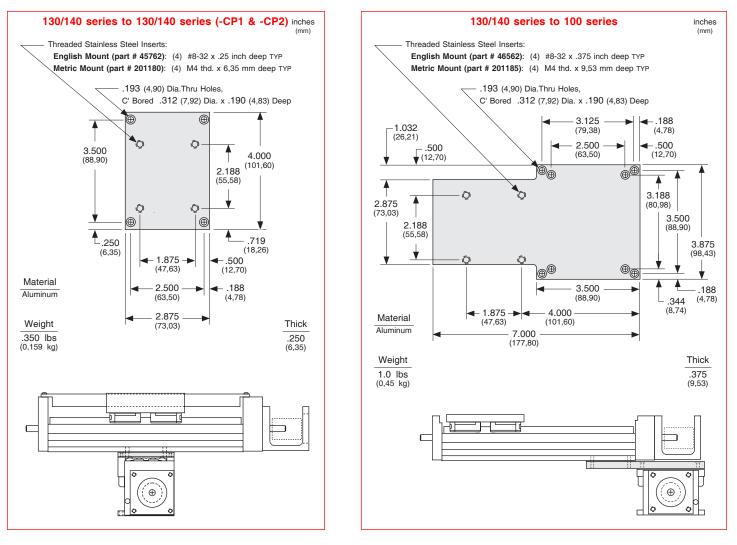
Moment of Inertia Values

The "moment of inertia" of an object is a gauge of the strength of that object to resist deflecting when used in an application or orientation where deflection might occur. The higher an I value relates to a lower amount of deflection.



Carriage Adapter Plates

Optional carriage adapter plates assist in the creation of simple X-Y, X-Z, and X-Y-Z multiple axis systems. One adapter plate allows a 130 or 140 series table to be mounted on top of any 130-CP1, 130-CP2, or 140-CP1 table to make an X-Y axes system. The second adapter plate allows any 130 or 140 series table to be mounted to any *LINTECH* 100, 110, and 120 series table. A precision square tool, or micrometer depth gauge, is required in order to obtain an orthogonality between the two tables of < 30 arc-seconds.





End of Travel (EOT) Switches & Home Switch

LINTECH provides several options for EOT & home switches. One style uses mechanically actuated switches, while other styles use "non-contact" versions. When ordered with a **LINTECH** 130 or 140 series table, each switch is mounted to the side of the table, while the actuating cams are mounted to the carriage assembly. The *T-slot* which runs along the one side of the 130 series, allows the switches to be located anywhere along the table. The switches are pre-wired by **LINTECH** for easy interfacing to the users Motion Controller.

End of Travel (EOT) Switches

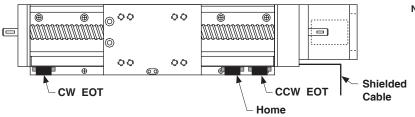
End of travel (EOT) switches can be utilized by a motion controller to stop carriage motion, thereby preventing any damage to personnel, table carriage, or user mounted load if the extreme end of travel has been reached by the carriage. There are two EOT switches mounted to the side of the table, one on each end. The CCW switch is mounted at the motor mount end, while the CW switch is located at the opposite end of the table. *LINTECH* provides normally closed (NC) end of travel switches. This provides for a power-off fail safe system, where the position controller can detect broken wires. *It is highly recommended that any positioning table used with a position controller, should have end of travel switches installed for protection of personnel, table carriage, and user mounted load.*

Home Switch

The home switch can be utilized by a motion controller as a known fixed mechanical location on the positioning table. The switch is located between the EOT switches, near the motor mount end, and is a normally open (NO) switch.

Switch Locations

The following diagram shows the locations of the switches when ordered from LINTECH.



Note: For the 130 or 140 series, EOT switches are normally located 0.125 inches (3 mm) inward from the maximum travel hard stops. Thus, reducing overall system travel by 0.25 inches (6 mm) from listed table travel for each model #.

Note: Each switch can be located anywhere along the T-slot which runs along the entire one side of the table.

Switch Type	Cost	Repeatability inches (microns)	Actuated	Power Supply Required	Activation Area inches (mm)	Comments
mechanical	least expensive	+/- 0.0002 (5)	mechanical	No	1.75 (44,45)	for most applications
reed	slightly more	+/- 0.0020 (50)	magnetic	No	0.30 (7,62)	for non-contact & low repeatable applications
hall effect	medium priced	+/- 0.0002 (5)	magnetic	Yes	0.32 (8,13)	for non-contact and wash down applications
proximity	most expensive	+/- 0.0002 (5)	non-magnetic	Yes	1.75 (44,45)	for non-contact, high speed, & wash down applications

Note: The repeatability of any switch is dependent upon several factors: carriage speed, accel rate, load weight, switch style, and the position controller. *LINTECH*'s ratings are based upon a carriage speed of 0.5 inches/sec (12.7 mm/sec) and a no load condition.

End of Travel (EOT) Switches & Home Switch

Mechanical Switches



Repeatability	
Electrical	

: +/- 0.0002 inch (5 microns)

Activation Style

Activation Area **Temperature Range**

Environment

Added Table Width

Individual Switch Wiring

: 5 amps @ 125 VAC
1 amp @ 85 VDC
: mechanical cam
: 1.75 inches (44,45 mm) of travel
: - 25° C to + 85° C
: non wash down

: 0.063 inch (1,6 mm) (EOT switches) 0.063 inch (1,6 mm) (with Home switch) : none

Non-Contact Reed Switches



Repeatability

Electrical

Activation Style

Activation Area

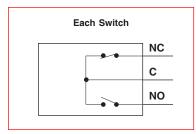
:	1.0 amps @ 125 VAC 0.5 amps @ 100 VDC
:	magnetic
:	0.30 inches (7,62 mm) of

: +/- 0.0020 inch (50 microns)

Temperature Range : - 10° C to + 60° C Environment : non wash down Added Table Width : none

Individual Switch Wiring

: 12 inch (305 mm) leads



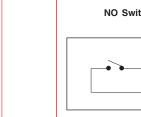
Standard *LINTECH* Wiring (provided when switch option is ordered with any table)

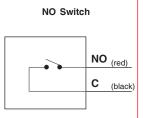
: from table end plate, 10 foot (3 m) shielded cable, 6 conductor, 24 AWG, unterminated leads

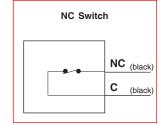
Wire Color	Description		
Black	CW EOT		
Blue	CW Common		
Red	CCW EOT		
White	CCW Common		
Brown	HOME		
Green	HOME Common	NO	
Silver	Shield		

Note: Hermetically sealed mechanical switches can be ordered as an option. This may be desired for "wash down" applications. Contact LINTECH.

Specifications subject to change without notice







travel

Standard *LINTECH* Wiring (provided when switch option is ordered with any table)

: from table end plate, 10 foot (3 m) shielded cable, 6 conductor, 24 AWG, unterminated leads

Wire Color	Description		
Black	CW EOT	(black)	
Blue	CW Common	(black) NC	
Red	CCW EOT	(black)	
White	CCW Common	(black) NC	
Brown	HOME	(red)	
Green	HOME Commor	n (black) NO	
Silver	Shield		

CW - Clockwise CCW - Counter Clockwise EOT - End of Travel - Normally Closed NC - Normally Open NO

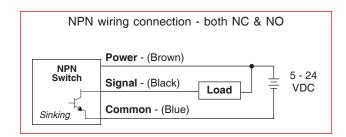


End of Travel (EOT) Switches & Home Switch

Non-Contact Hall Effect Switches



Repeatability	: +/- 0.0002 inch (5 microns)
Electrical	: 5 - 24 VDC 15 mA - power input 25 mA max - signal
Actuation Style	: magnetic
Activation Area	: 0.32 inches (8,13 mm) of travel
Temperature Range	: - 10° C to + 60° C
Environment	: wash down
Added Table Width	: none
Individual Switch Wiring	: 12 inch (305 mm) leads



Standard *LINTECH* Wiring : from table end plate, (provided when switch option is ordered with any table)

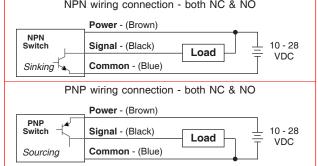
10 foot (3 m) shielded cable; 9 conductor, 24 AWG, unterminated leads

Wire Color	D	escription		
Brown	CW Power	(brown)	-[1
Black	CW EOT	(black)	switch	NC
Blue	CW Common	(blue)		
Red	CCW Power	(brown)		1
White	CCW EOT	(black)	switch	NC
Green	CCW Common	(blue)		
Orange	Home Power	(brown)	-[1
Yellow	Home	(black)	switch	NO
Grey	Home Common	(blue)		
Silver	Shield			

Non-Contact Proximity Switches



Repeatability	: +/- 0.0002 inch (5 microns)
Electrical	: 10 - 28 VDC 15 mA - power input 100 mA max - signal
Actuation Style	: non-magnetic cam
Activation Area	: 1.75 inches (44,45 mm) of travel
Temperature Range	: - 25° C to + 75° C
Environment	: IEC IP67 wash down
Added Table Width	: 0.20 inch (5,1 mm) (EOT switches) 0.20 inch (5,1 mm) (Home switch)
Individual Switch Wiring	: 6.5 foot (2 m) cable for NPN : 3.3 foot (1 m) cable for PNP
NPN wiring cor	prection - both NC & NO



Standard *LINTECH* Wiring : from table end plate, (provided when switch option is ordered with any table)

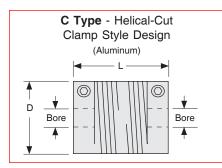
10 foot (3 m) shielded cable; 9 conductor, 24 AWG, unterminated leads

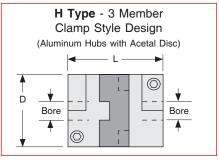
Wire Color	Description					
Brown	CW Power	(brown)	1	1		
Black	CW EOT	(black)	switch	NC		
Blue	CW Common	(blue)	-			
Red	CCW Power	(brown)		1		
White	CCW EOT	(black)	switch	NC		
Green	CCW Common	(blue)	-			
Orange	Home Power	(brown)	4	1		
Yellow	Home	(black)	switch	NO		
Grey	Home Common	(blue)				
Silver	Shield					

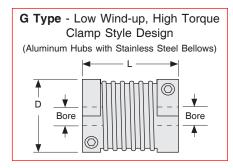
Options

Motor Couplings

LINTECH provides three different types of couplings that can be used to mount a motor to a positioning table. These couplings compensate for misalignment between the motor shaft & screw shaft extension. This provides for trouble-free operation as long as certain precautions are taken. The connected motor output torque should never exceed the coupling maximum torque capacity. Larger capacity couplings may be required for applications having high accelerations, large back driving loads, high torque output motors, or servo motors.







Model	D	L		Bore	e Diam	eters			Weight	Inertia	Wind-up	Max Torque
Number	inches (mm)	inches (mm)	Table	Motor	Minii (in)			<i>imum</i> (mm)	ounces (grams)	oz-in² (g-cm²)	arc-sec/oz-in (deg/N-m)	oz-in (N-m)
C100-312-aaa	1.00 (25,4)	1.50 (38,1)	312	aaa	.250	6	.375	10	1.5 (43)	.19 (35)	23.0 (0,9)	400 (2,8)
C125-312-aaa ⁽¹⁾	1.25 (31,8)	2.00 (50,8)	312	aaa	.250	6	.500	14	3.5 (99)	.68 (124)	15.0 (0,59)	700 (4,9)
H100-312-aaa	1.00 (25,4)	1.28 (32,5)	312	aaa	.250	6	.375	10	1.2 (34)	.15 (27)	7.2 (0,28)	450 (2,8)
H131-312-aaa ⁽¹⁾	1.31 (33,3)	1.89 (48,0)	312	aaa	.250	6	.625	16	2.9 (82)	.62 (114)	2.5 (0,098)	1,000 (7,1)
G100-312-aaa	0.99 (25,2)	1.26 (32,0)	312	aaa	.250	6	.500	12	1.3 (36)	.16 (29)	1.0 (0,39)	500 (3,5)
G126-312-aaa	1.26 (32,1)	1.62 (41,0)	312	aaa	.250	6	.625	16	2.7 (74)	.54 (99)	0.3 (0,012)	1,100 (7,7)
Possible values for aaa	375 = 500 =	.250 inch .375 inch .500 inch .625 inch	003 004 003 014	6 = 6 mr 8 = 8 mr	m m	012 = 014 = 016 =		m				

Footnotes:

(1) This coupling option can not be used with the optional NEMA 23 motor mount because its length is too long. However, this coupling option can be used with the optional NEMA 34 motor mount. Custom motor mounts can be provided upon request. See page B-39 for maximum coupling diameter and length specifications for use with the optional NEMA 23 & 34 motor mounts.

Motor Couplings

Coupling	Cost	Torque Capacity	Wind-up	Suggested Motor	Comments
С Туре	least expensive	light	the most	stepper	ideal for most step motor applications
Н Туре	medium priced	medium	medium	stepper or servo	use for high accels & for starting & stopping large inertia loads
G Туре	most expensive	high	the least	servo	use for very high torque requirements & very high servo accelerations

Specification	130 Series	130 Series	140 Series	140 Series			
	NEMA 23 bracket	NEMA 34 bracket	NEMA 23 bracket	NEMA 34 bracket			
opeonodion	inches	inches	inches	inches			
	(mm)	(mm)	(mm)	(mm)			
Shaft extension diameter at motor mount end	0.312	0.312	0.375	0.375			
	(7,92)	(7,92)	(9,53)	(9,53)			
Maximum coupling diameter	1.500	1.500	1.500	2.000			
	(38,10)	(38,10)	(38,10)	(50,80)			
Maximum coupling length	1.750	2.250	1.900	2.375			
	(44,45)	(57,15)	(48,26)	(60,32)			
Note: Custom brackets available upon request.							

Coupling Part Numbers

C020 C021 C022 C023 C024 C040 C041 C042 C043 C044 C045 C046 C047	C100-312-250 C100-312-375 C100-312-006 C100-312-008 C100-312-010 C125-312-250 C125-312-375 C125-312-500 C125-312-006 C125-312-010 C125-312-010 C125-312-014	C125 C126 C127 C128 C129 C130 C131 C132 C133 C134 C145 C146 C147 C148 C147 C148 C149 C150 C151 C152 C153 C154	H100-312-250 H100-312-375 H100-312-006 H100-312-008 H100-312-010 H100-375-250 H100-375-375 H100-375-006 H100-375-008 H100-375-010 H131-312-250 H131-312-500 H131-312-500 H131-312-500 H131-312-006 H131-312-010 H131-312-010 H131-312-014 H131-312-016	C155 C156 C157 C158 C159 C160 C161 C162 C163 C164 C190 C191 C192 C193 C194 C195 C196 C197 C198 C199 C200	H131-375-375 H131-375-500 H131-375-625 H131-375-006 H131-375-008 H131-375-010 H131-375-010 H131-375-012 H131-375-014 H131-375-016	C400 C401 C402 C403 C404 C405 C406 C407 C408 C409 C410 C411 C412 C413 C412 C413 C425 C426 C427 C428 C429 C430 C431 C431 C432 C433	G100-312-250 G100-312-375 G100-312-500 G100-312-006 G100-312-008 G100-312-010 G100-312-010 G100-375-250 G100-375-250 G100-375-500 G100-375-008 G100-375-008 G100-375-010 G126-312-250 G126-312-250 G126-312-500 G126-312-006 G126-312-008 G126-312-010 G126-312-012 G126-312-014	C435 C436 C437 C438 C439 C440 C441 C442 C443 C444 C443 C444 C470 C471 C472 C473 C474 C475 C476 C477 C478 C479 C480	G126-375-250 G126-375-375 G126-375-500 G126-375-625 G126-375-006 G126-375-010 G126-375-012 G126-375-012 G126-375-014 G126-375-016 G158-375-375 G158-375-500 G158-375-625 G158-375-625 G158-375-010 G158-375-012 G158-375-014 G158-375-018 G158-375-019 G158-375-020
						C434	G126-312-016		

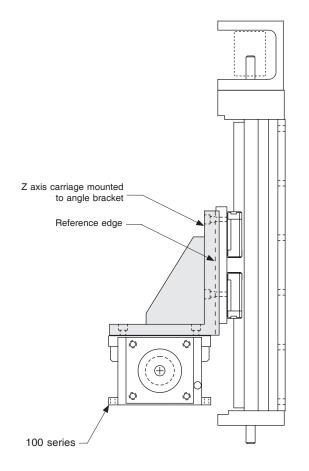
Vertical Angle Brackets

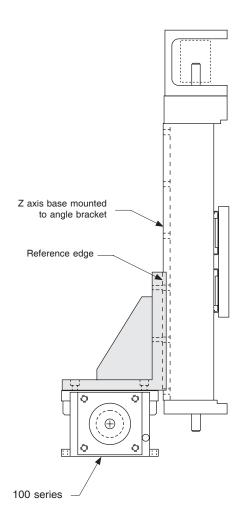
LINTECH has provided a simple solution for those applications requiring a Z axis within a multiple axis configuration. Two different vertical angle brackets are available. One allows a 130 or 140 series Z axis table to be mounted to a second 130 or 140 series table. The other vertical angle bracket allows a 130 or 140 series Z axis table to be mounted to a 100 series table. The 100 series table has a higher dynamic load and moment load capacity.

These precision machined aluminum angle brackets ensure that the orthogonality of the two tables is maintained to < 30 arc-seconds. To achieve this orthogonality, one side of the angle bracket must be mounted to the table carriage with a precision square tool or micrometer depth gauge, while the second axis is mounted securely against the reference edge of the angle bracket. The angle bracket hole pattern is preengineered for easy mounting of either the table carriage or table base.

When ordered, the angle bracket is shipped separately from the tables. The user is required to assemble the angle bracket to the tables. However, if requested to, *LINTECH* can pre-assemble the multiple axis system before shipping. Anytime an angle bracket is used for multiple axis configurations, moment loads will result on one or more axes. Be sure to review moment loads, and the positioning table life, for your application.

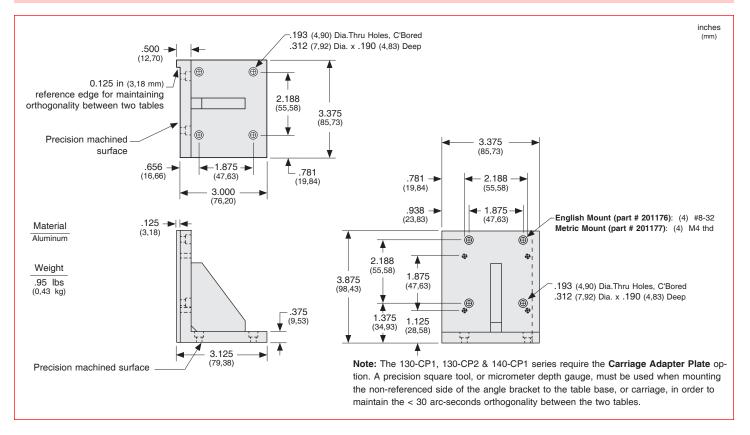
Either the 130 or 140 series base or carriage can be mounted to either vertical angle bracket.



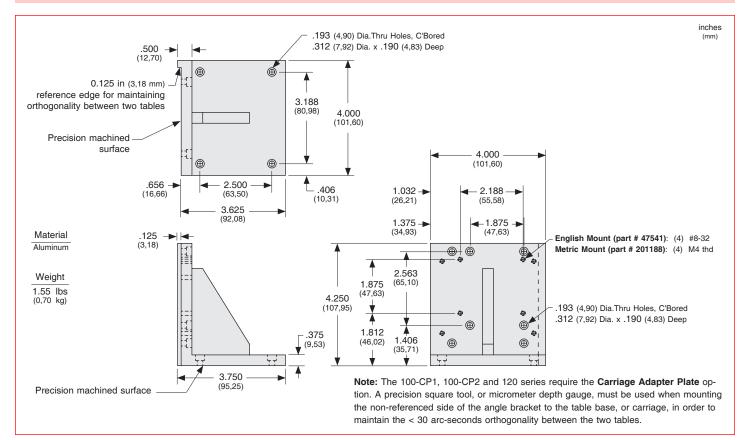




Vertical Angle Bracket (130 or 140 series to 130 or 140 series)

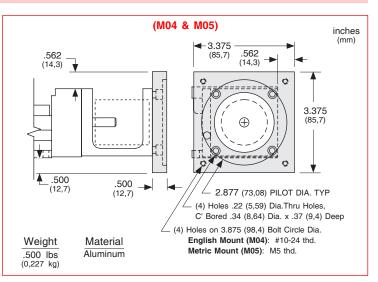


Vertical Angle Bracket (130 or 140 series to 100 series)



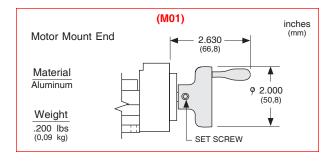
NEMA 34 Motor Mount for 130 Series

The NEMA 34 motor adapter bracket is an aluminum flange that mounts to the front of the NEMA 23 motor mount. The bracket can be ordered in either an English, or Metric motor mount. *LINTECH* can provide adapter brackets for any step motor, or servo motor, that has other mounting requirements.



Hand Crank

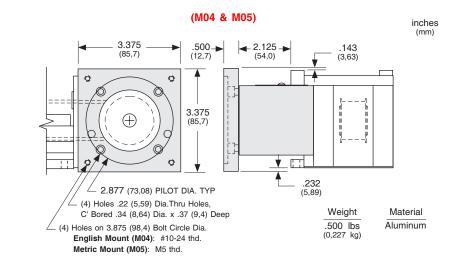
For manually operated applications, *LINTECH* provides a hand crank option for the 130 table series. The hand crank replaces the motor mount and coupling on the table.



LINTECH[®]

NEMA 34 Motor Mount for 140 Series

The 140 series positioning table can be provided with an optional NEMA 34 motor adapter bracket. The bracket can be ordered in either an English, or Metric motor mount. *LINTECH* can provide adapter brackets for any step motor, or servo motor, that has other mounting requirements.



Chrome Plated Linear Bearings, Rails, and Screws

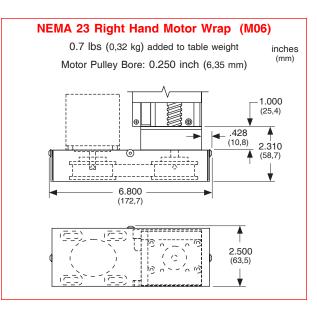
For applications in high moisture, high humidity, clean room, or highly corrossive environments, chrome plating of the linear bearings, linear rails, and screw will offer superior resistance to corrosion than stainless steel components, resulting in longer table life. The process uniformly deposits dense, hard, high chromium alloy on the rails or screw, and has a Rockwell C hardness value of 67-72. This process also conforms to MIL Spec: (MIL-C-23422). The chrome plating bonds to the parent material and will not crack or peel off under the high point loading of balls on the rail, or screw. This chrome plating process differs from a normal hard chrome plate which just lays on the surface of the part plated.

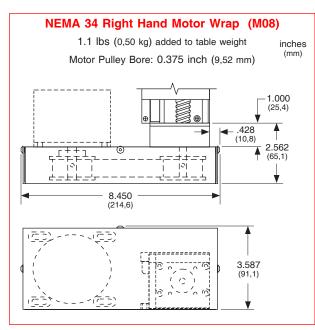
Specifications subject to change without notice

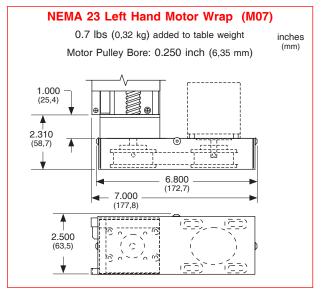
www.LintechMotion.com

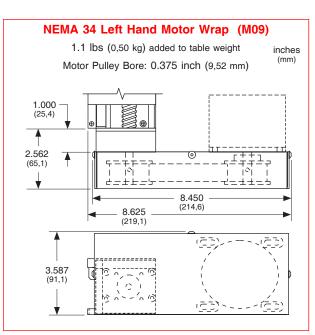
Motor Wrap Packages

For space limited 130 series applications, a belt and pulley system can couple the screw shaft extension to the motor shaft. This wraps the motor parallel to the table in order to decrease the overall positioning system length. Pulley weights and diameters are given in order to assist in calculating motor torque requirements.









Motor Wrap Frame Size	Motor Pulley Dia. inches (mm)	Motor Pulley Wt. ounces (kg)	Screw Pulley Dia. inches (mm)	Screw Pulley Wt. ounces (kg)	Belt Weight ounces (kg)
NEMA 23	1.65	7.5	1.65	7.5	1.0
	(41,9)	(0,21)	(41,9)	(0,21)	(0,028)
NEMA 34	1.65	8.0	1.65	8.0	1.2
	(41,9)	(0,23)	(41,9)	(0,23)	(0,034)

Note: Motor pulley & belt shipped "loose". No motor mount nuts & bolts are provided. Custom motor wrap packages are available upon request. Other motor pulley bores MUST be specified for non-NEMA motors.

Power-off Electric Brakes

For vertical table applications, or for those applications requiring the load to be locked securely in place, an electric brake may be mounted to the positioning table. The 130 series will have the brake mounted to the screw shaft extension located on the table end, opposite the motor mount bracket. The 140 series will have the brake mounted to the thru drive shaft option. With proper wiring from a control system, this power-off friction brake can ensure that the carriage is firmly held in place, when no electric power is applied to the brake. When power is applied to the brake, the brake is opened or "released".

For proper emergency braking of the positioning table, this electric brake needs to be interfaced to a position controller or relay network. LINTECH also provides 24 & 90 VDC power supplies which can be used to power the brakes.

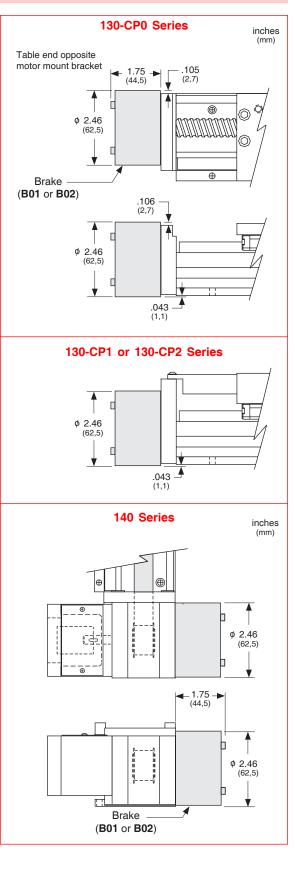
Brakes

Model	Holding Force	Excitation Voltage	Current	Weight
Number	in-lbs (N-m)	volts	amps	lbs (kg)
B01	18 (2,0)	24 VDC	0.733	1.4 (0,62)
B02	18 (2,0)	90 VDC	0.178	1.4 (0,62)

Note: This power-off electric brake MUST NOT be engaged when the positioning table is in motion. Moving the table with the brake applied could damage the brake and the positioning table. Also, continuous use of this brake to stop a table (load) that is in motion could damage the brake and the positioning table. Dynamic braking of a positioning table should be done by the motor and not the brake.

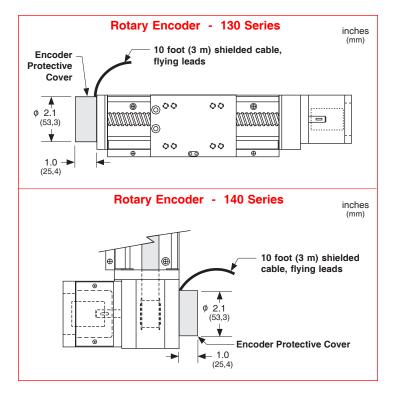
Power Supplies

Model		DC Out	put	AC Input		
Number	volts	amps	style	volts	amps	Hz
41970	5	3.0	regulated	120 / 240	0.8 / 0.4	47-63
37488	24	1.2	regulated	120 / 240	0.8 / 0.4	47-63
37489	90	0.8	unregulated	120	1.0	50/60
37490	90	0.8	unregulated	240	0.5	50/60

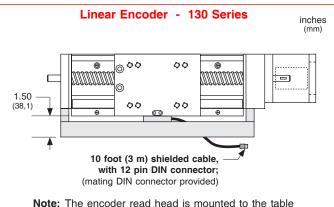


Linear & Rotary Incremental Encoders

Fully enclosed, incremental, optical linear encoders can be mounted on the side of any *LINTECH* 130 series. Shaftless, incremental, optical rotary encoders can be mounted to the screw shaft extension on the opposite end from the motor mount end on the 130 or 140 series positioning tables. These encoders provide positional feedback to either a motion controller, or a digital position display.



LI	NEAR	ROTARY	Description
Din Pin #	Wire Color	Wire Color	Description
С	Green	White	Channel A ⁺ (or A)
D	Yellow	Blue	Channel A ⁻ (or \overline{A})
Е	Pink	Green	Channel B⁺ (or B)
L	Red	Orange	Channel B ⁻ (or \overline{B})
G	Brown	White/Black	Channel Z ⁺ (or Z)
Н	Grey	Red/Black	Channel Z ⁻ (or \overline{Z})
А	Shield		Case ground
В	White	Black	Common
К	Black	Red	+ 5 vdc (+/- 5%)



Note: The encoder read head is mounted to the table carriage with the encoder lip seal facing down.

Specification		ROTARY ENCODERS		LINEAR ENCODERS		
	E01	E02	E03	E10	E11	
Line Count	500 lines/rev	1000 lines/rev	1270 lines/rev	2500 lines/inch	125 lines/mm	
Pre Quadrature Resolution	0.002 revs/pulse	0.001 revs/pulse	0.00079 revs/pulse	0.0004 inch/pulse	8 microns/pulse	
Post Quadrature Resolution	0.0005 revs/pulse	0,00025 revs/pulse	0.00019 revs/pulse	0.0001 inch/pulse	2 micron/pulse	
Accuracy				+/- 0.0002 in/40"	+/- 5 microns/m	
Maximum Speed		50 revs/sec	79 inches/sec	2 m/sec		
Maximum Accel		40 revs/sec ²		130 ft/sec ²	40 m/sec ²	
Excitation Power		+ 5 VDC @ 125 ma		+ 5 VDC @ 150 ma		
Operating Temperature	32º F	to 140° F (0° C to 6	0° C)	32° F to 120° F (0° C to 50° C)		
Humidity	20%	% to 80% non condens	sing	20% to 80% non condensing		
Shock	10) G's for 11 msec durati	on	15 G's for 8 msec duration		
Weight	0.7 lbs (0,283 kg)			0.7 oz/inch (0,00078 kg/mm) length of scale + 0.5 lbs (0,23 kg) read head and brackets		
Cable Length	10 ft (3 r	n), unterminated 26 gau	ge leads	10 ft (3 m) with	DIN connector	
Zero Reference Output		Once per revolution	At center of e	ncoder length		
Outputs	TTL	. square wave; Two cha	annel (A+ & B+); Differe	ential (A- & B-); Line Di	river	

Notes